

Operator's manual

SILENO city, smart SILENO city

 **GARDENA**[®]

gardena.com



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1 Introduction

1.1 Memo

Serial number:	
PIN code:	
Product registration key:	
<p>The Product registration key is a valuable document and must be stored in a safe place. This key is necessary for example to register the product on GARDENA's website or unlock the robotic lawnmower in the event of a lost PIN code. The product registration key is provided in a separate document in the product packaging.</p> <p>If the robotic lawnmower is stolen, it is important to notify GARDENA of this. Contact GARDENA customer service and provide the robotic lawnmower's serial number so that it can be registered as stolen in an international data-base. This is an important step in the robotic lawnmower's theft protection which reduces interest in the buying and selling of stolen robotic lawnmowers.</p> <p>The product's serial number consists of 9 digits and is shown on the product rating plate and packaging.</p> <p style="text-align: center;">www.gardena.com</p>	

1.2 Product description

Congratulations on your choice of an exceptionally high quality product. To get the best results from your GARDENA robotic lawnmower requires knowledge of how it works. This Operator's Manual contains important information about the robotic lawnmower, how it must be installed and how to use it. As a complement to this Operator's Manual, there are information movies with instructions available on GARDENA's website, www.gardena.com.

Keep in mind that the operator is responsible for accidents or hazards occurring to other people or their property.

GARDENA has a policy of continuous product development and reserves the right to modify the design, appearance and function of products without prior notice.

1.2.1 Capacity

The robotic lawnmower is recommended for lawn sizes up to maximum capacity listed in the *Technical data on page 51*.

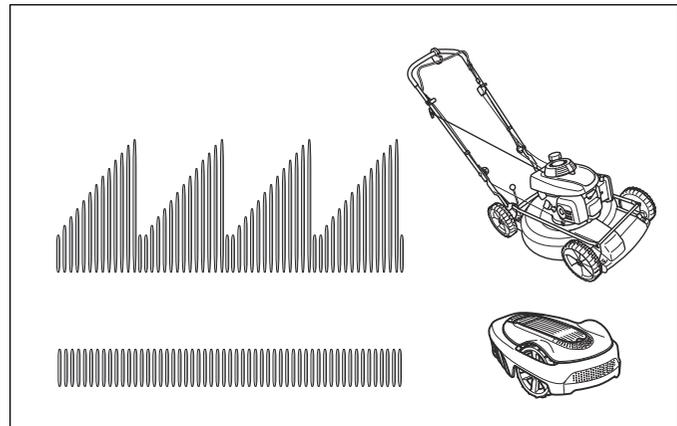
How big an area the robotic lawnmower can keep cut depends primarily on the condition of the blades and the type, growth and moisture of the grass. The shape of the lawn is also significant. If the garden mainly consists of open lawn areas, the robotic lawnmower can mow more per hour than if the garden consists of several small lawns separated by trees, flower beds and passages.

A fully charged robotic lawnmower mows for 60 to 80 minutes depending on the status of the battery and lawn. Then the robotic lawnmower will charge for 60 to 70 minutes. The charging time can vary depending on factors like the ambient temperature.

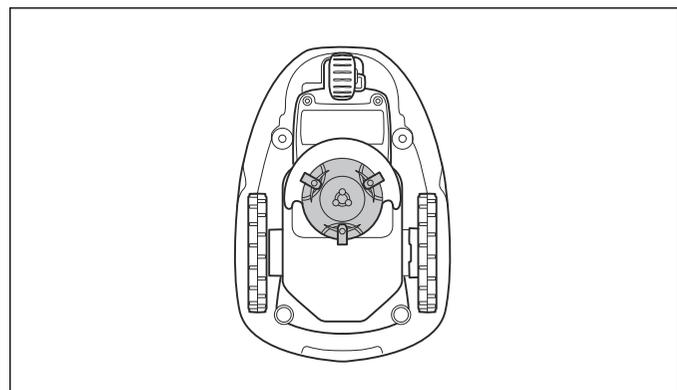
1.2.2 Mowing technique

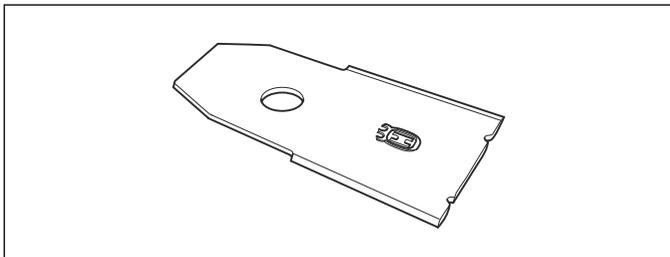
The robotic lawnmower's system is based on an efficient and energy saving principle. Unlike many standard lawnmowers, the robotic lawnmower cuts the grass instead of knocking it off. This frequent cutting technique improves the grass quality. No collection of grass is

required, and small pieces of cut grass will reduce the need of fertilizers. Furthermore, it is emission free, convenient and your lawn will always look well maintained.



It is recommended to let the robotic lawnmower to mainly mow in dry weather to obtain the best possible result. The robotic lawnmower can also mow in the rain, however wet grass easily sticks on the robotic lawnmower and there is a greater risk of slipping on steep slopes.





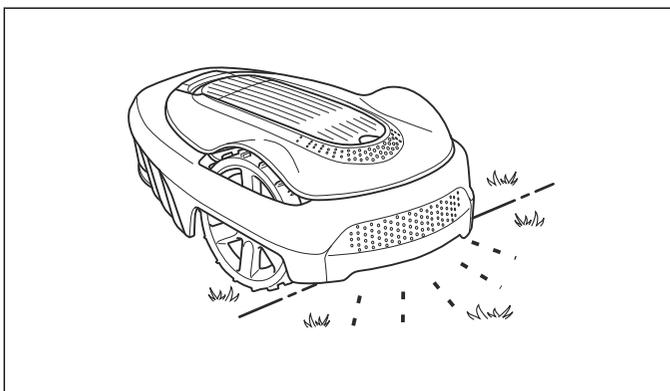
The blades must be in good condition to obtain the best mowing result. In order to keep the blades sharp for as long as possible it is important to keep the lawn free from branches, small stones and other objects.

Replace the blades regularly for the best mowing result. See *Replace the blades on page 38*.

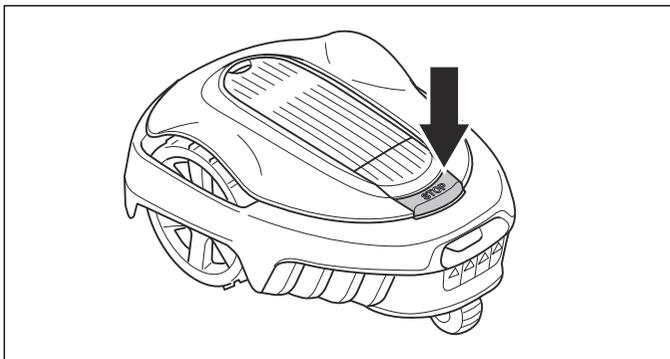
1.2.3 Working method

The robotic lawnmower automatically mows the lawn. It continuously alternates between mowing and charging.

When the robotic lawnmower body hits an obstacle or approaches the boundary wire the robotic lawnmower reverses and selects a new direction. Sensors at the front and back will sense when the robotic lawnmower is approaching the boundary wire. The front of the robotic lawnmower always passes the boundary wire by a specific distance before the mower turns around. The distance can be changed to adapt to the installation if required.

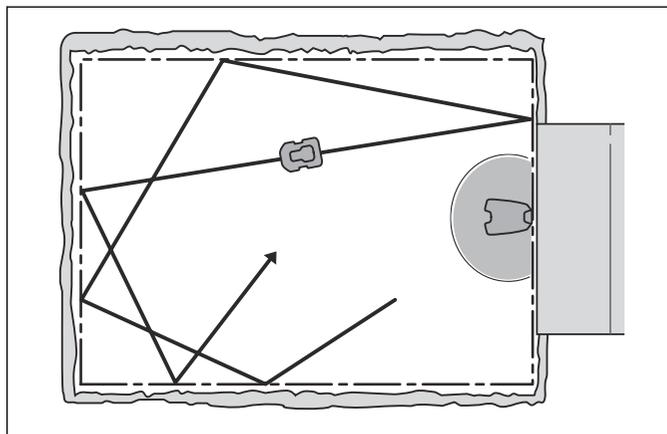


The **STOP** button on the top of the robotic lawnmower is used to stop the robotic lawnmower from operating out on the lawn. The **STOP** button also needs to be pressed if the robotic lawnmower is in an active status, but standing still in the charging station. After **STOP** is pressed it is possible to press the keypad and, for example, go into the menu or change operating mode. The PIN code must be entered and confirmed by pressing the **OK** button before it is possible to start again. The PIN code together with pressing the **Start** button act as a start inhibitor.



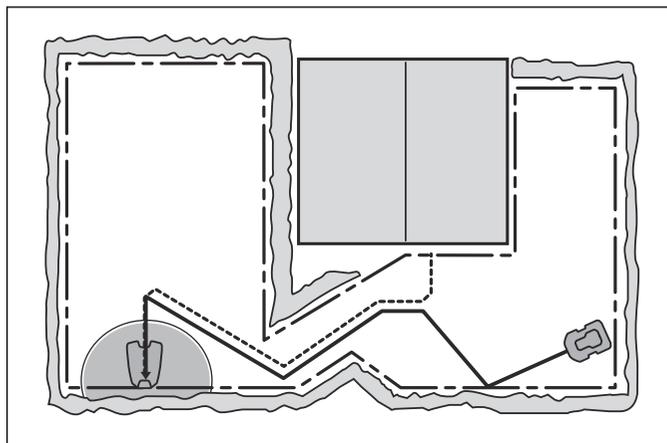
1.2.4 Movement pattern

The movement pattern of the robotic lawnmower is random, which means that a movement pattern is never repeated. With this cutting system the lawn is mown evenly without any mowing lines from the robotic lawnmower.

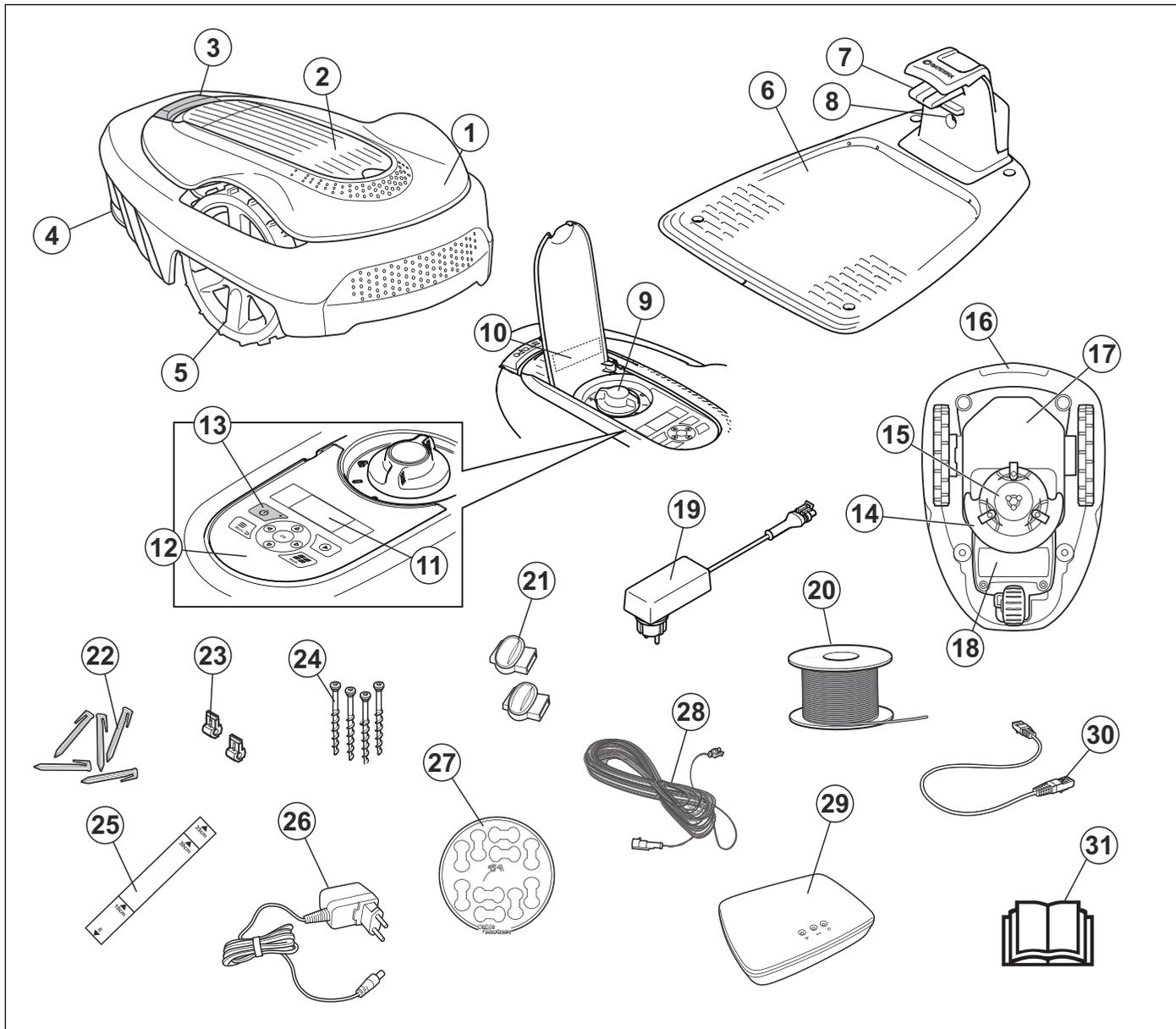


1.2.5 Finding the charging station

The robotic lawnmower operates irregularly until it reaches the guide wire. Then it follows the guide wire to the charging station. The guide wire is a wire that is laid from the charging station towards, for instance, a remote part of the working area or through a narrow passage. It is connected with the boundary wire and makes it much easier and faster for the robotic lawnmower to find the charging station.



1.3 Product overview

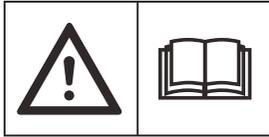


The numbers in the figure represent:

1. Body
2. Hatch to display and keypad
3. Stop button
4. Rear wheel
5. Front wheels
6. Charging station
7. Contact strips
8. LED for operation check of the charging station and boundary wire
9. Cutting height adjustment
10. Rating plate
11. Display
12. Keypad
13. ON/OFF button
14. Cutting system
15. Blade disc
16. Handle
17. Chassis box with electronics, battery and motors
18. Battery cover
19. Power supply (the appearance of the power supply may differ depending on market)
20. Loop wire for boundary loop and guide wire
21. Couplers for loop wire
22. Pegs
23. Connector for the loop wire
24. Screws for securing the charging station
25. Measurement gauge for help when installing the boundary wire (the measurement gauge is broken loose from the box)
26. smart gateway power supply (only for smart SILENO city)
27. Cable markers
28. Low voltage cable
29. smart gateway (only for smart SILENO city)
30. smart gateway LAN-cable (only for smart SILENO city)
31. Operator's Manual and Quick Guide

1.4 Symbols on the product

These symbols can be found on the robotic lawnmower. Study them carefully.



WARNING: Read the user instructions before operating the robotic lawnmower.



WARNING: Operate the disabling device before working on or lifting the machine.

It is only safe to carry out inspection or maintenance on the robotic lawnmower when the robotic lawnmower is disabled. The robotic lawnmower is disabled when the lamp on the **ON/OFF** button is not lit.



WARNING: Keep a safe distance from the machine when operating. Keep your hands and feet away from the rotating blades.



WARNING: Do not ride on the machine. Never put your hands or feet close to or under the machine.



This product conforms to the applicable EC Directives.



Noise emission to surroundings. The product's emissions are set out in *Technical data on page 51* and on the rating plate.



It is not permitted to dispose this product as normal household waste. Ensure that the product is recycled in accordance with local legal requirements.



The low voltage cable must not be shortened, extended or spliced.

Do not use a trimmer nearby the low voltage cable. Be careful when trimming edges where the cables are placed.

Operate the disabling device before you use or lift the product.

2 Safety

2.1 Safety definitions

Warnings, cautions and notes are used to point out specially important parts of the operator's manual.



WARNING: Used if there is a risk of injury or death for the operator or bystanders if the instructions in the manual are not obeyed.



CAUTION: Used if there is a risk of damage to the product, other materials or the adjacent area if the instructions in the manual are not obeyed.

Note: Used to give more information that is necessary in a given situation.

2.2 General safety instructions

The following system is used in the Operator's Manual to make it easier to use:

- Text written in *italics* is a text that is shown on the robotic lawnmower's display or is a reference to another section in the Operator's Manual.
- Text written in **bold** is one of the buttons on the robotic lawnmower's keypad.
- Text written in *UPPERCASE* and *italics* refer to the different operating modes available in the robotic lawnmower.

2.2.1 IMPORTANT. READ CAREFULLY BEFORE USE. KEEP FOR FUTURE REFERENCE

The operator is responsible for accidents or hazards occurring to other people or property.

This appliance is not intended for use by persons (including children) with reduced physical, sensory or mental capabilities, or lack of experience and knowledge, unless they have been given supervision or instruction concerning use of the appliance by a person responsible for their safety. Children should be supervised to ensure that they do not play with the appliance.

This appliance can be used by children aged from 8 years and above and persons with reduced physical, sensory or mental capabilities or lack of experience and knowledge if they have been given supervision or instruction concerning use of the appliance in a safe way and understand the hazards involved. Local regulations may restrict the age of the operator. Clearing and maintenance shall not be made by children without supervision.

Never connect the power supply to an outlet if plug or cord is damaged. Worn or damaged cord increase the risk of electric shock.

Only charge the battery in the included charging station. Incorrect use may result in electric shock, overheating or leaking of corrosive liquid from the battery. In the event of leakage of electrolyte flush with water/neutralizing agent, seek medical help if it comes in contact with the eyes.

Use only original batteries recommended by the manufacturer. Product safety cannot be guaranteed with other than original batteries. Do not use non-rechargeable batteries.

The appliance must be disconnected from the supply mains when removing the battery.



WARNING: The robotic lawnmower can be dangerous if used incorrectly.



WARNING: Never use the robotic lawnmower when persons, especially children or pets, are in the cutting area.

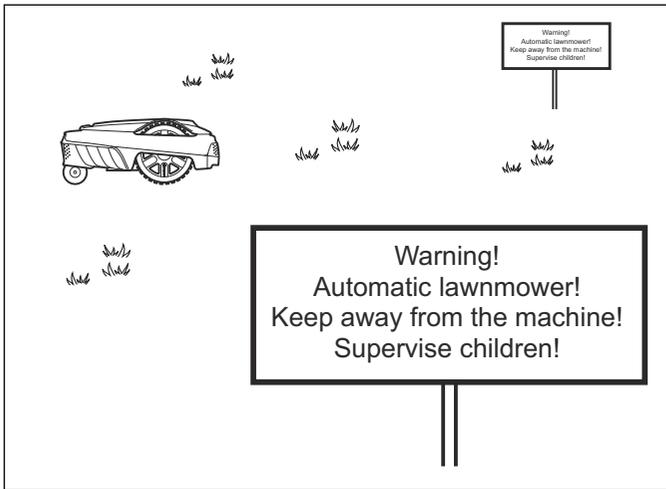


WARNING: Keep your hands and feet away from the rotating blades. Never put your hands or feet close to or under the machine when the motor is running.

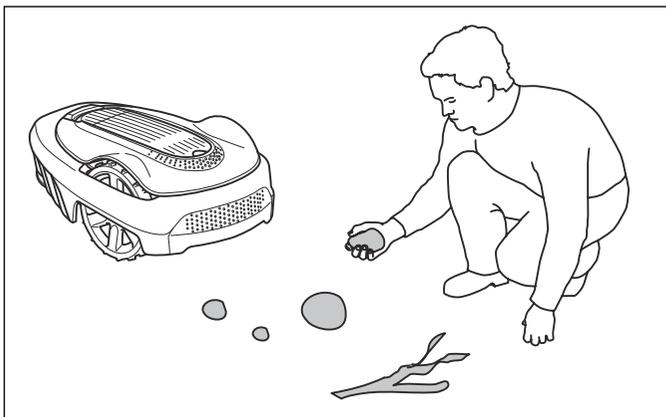
2.3 Safety instructions for operation

2.3.1 Use

- This robotic lawnmower is designed to mow grass in open and level ground areas. It may only be used with the equipment recommended by the manufacturer. All other types of use are incorrect. The manufacturer's instructions with regard to operation/maintenance must be followed precisely.
- Warning signs shall be placed around the working area of the robotic lawnmower if it is used in public areas. The signs shall have the following text:
Warning! Automatic lawnmower! Keep away from the machine! Supervise children!



- Use the operating mode *Park* or turn off the robotic lawnmower when persons, especially children or pets, are in the cutting area. It is recommended to program the lawnmower for use during hours when the area is free from activity, e.g. at night. See *Advanced on page 23*.
- The robotic lawnmower may only be operated, maintained and repaired by persons that are fully conversant with its special characteristics and safety regulations. Please read the Operator's Manual carefully and make sure you understand the instructions before using the robotic lawnmower.
- It is not permitted to modify the original design of the robotic lawnmower. All modifications are made at your own risk.
- Check that there are no stones, branches, tools, toys or other objects on the lawn that can damage the blades. Objects on the lawn can also lead to the robotic lawnmower getting stuck in them and help may be required to remove the object before the mower can continue mowing. Always turn off the robotic lawnmower using the **ON/OFF** button before clearing a blockage..



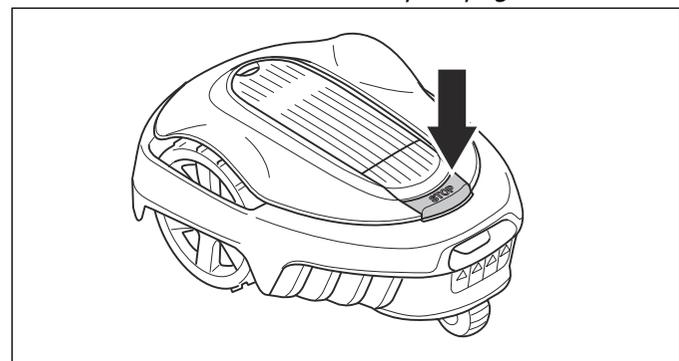
- Start the robotic lawnmower according to the instructions. When the robotic lawnmower is turned on, make sure to keep your hands and feet away from the rotating blades. Never put your hands and feet under the robotic lawnmower.
- Never touch moving hazardous parts, such as the blade disc, before it has come to a complete stop.
- Never lift up the robotic lawnmower or carry it around when it is turned on.
- Do not let persons who do not know how the robotic lawnmower works and behaves use it.

- The robotic lawnmower must never be allowed to collide with persons or other living creatures. If a person or other living creature comes in the lawnmower's way it shall be stopped immediately. See *Advanced on page 23*.
- Do not put anything on top of the robotic lawnmower or its charging station.
- Do not allow the robotic lawnmower to be used with a defective guard, blade disc or body. Neither should it be used with defective blades, screws, nuts or cables. Never connect a damaged cable, or touch a damaged cable before it is disconnected from the supply.
- Do not use the robotic lawnmower if the **ON/OFF** button does not work.
- Always switch off the robotic lawnmower using the **ON/OFF** button when the robotic lawnmower is not in use. The robotic lawnmower can only start when the **ON/OFF** button has been turned on and the correct PIN code has been entered.
- The robotic lawnmower must never be used at the same time as a sprinkler. Use the schedule function (see *Advanced on page 23*) so the mower and sprinkler never run simultaneously.
- GARDENA does not guarantee full compatibility between the robotic lawnmower and other types of wireless systems such as remote controls, radio transmitters, hearing loops, underground electric animal fencing or similar.
- Metal objects in the ground (for example reinforced concrete or anti-mole nets) can result in a stoppage. The metal objects can cause interference with the loop signal which then can lead to a stoppage.
- The robotic lawnmower must never be stored, operated or charged in temperatures below 0 °C or above 50 °C. This might cause damage to the product.

2.3.2 How to lift and move the robotic lawnmower

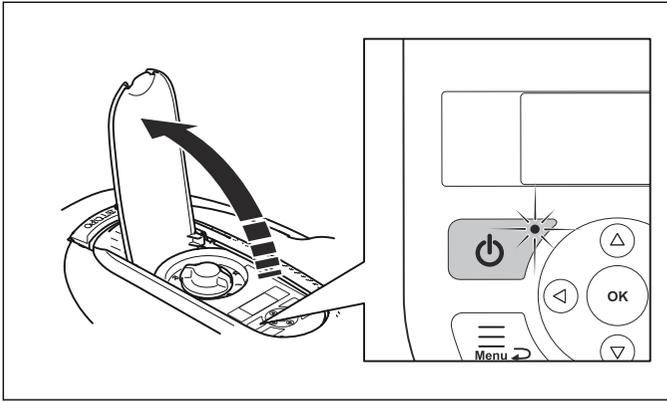
To safely move from or within the working area:

1. Press the **STOP** button to stop the robotic lawnmower. If security is set to high level (see *Security level on page 25*) the PIN code has to be entered. The PIN code contains four digits and is selected when you start the robotic lawnmower for the first time. See *First start-up on page 20*.



2. Press the **ON/OFF** button and make sure the robotic lawnmower is turned off. Check that the indicator lamp on the **ON/OFF** button is not lit. This means

that the robotic lawnmower is disabled. See *The indicator lamp on page 35*.



3. Carry the robotic lawnmower by the handle under the robotic lawnmower with the blade disc away from the body.

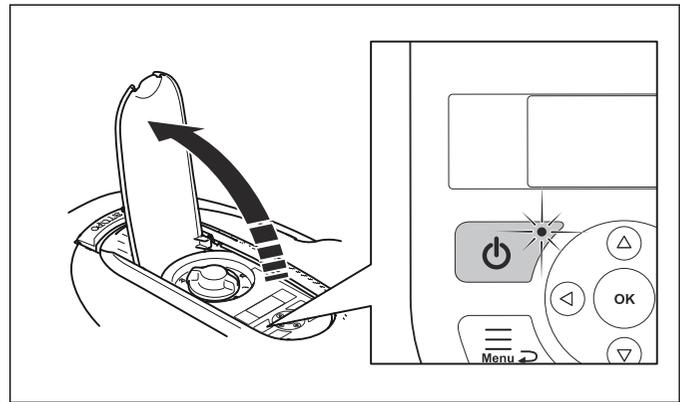


WARNING: The robotic lawnmower must be turned off before lifting it. The robotic lawnmower is disabled the indicator lamp on the **ON/OFF** button is not lit.

CAUTION: Do not lift the robotic lawnmower when it is parked in the charging station. It can damage the charging station and/or the robotic lawnmower. Press **STOP** and pull the robotic lawnmower out of the charging station before lifting it.

2.3.3 Maintenance

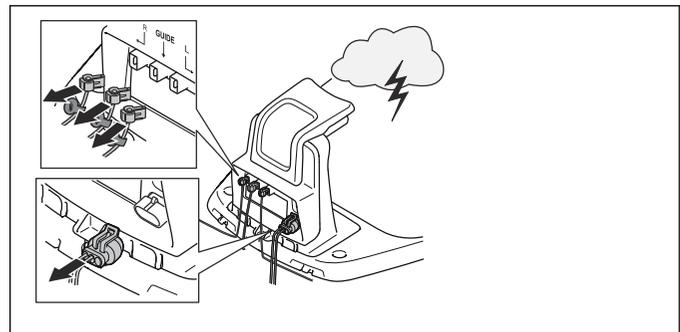
WARNING: The robotic lawnmower must be turned off before any maintenance is done. The robotic lawnmower is disabled when the indicator lamp on the **ON/OFF** button is not lit.



CAUTION: Never use a high-pressure washer to clean the robotic lawnmower. Never use solvents for cleaning.

Inspect the robotic lawnmower each week and replace any damaged or worn parts. See *Introduction - maintenance on page 38*.

2.3.4 In the event of a thunderstorm



CAUTION: Disconnect all connections to the charging station (power supply, boundary wire and guide wire) if there is a risk of a thunderstorm.

1. Make sure the wires are marked with the supplied markers to simplify reconnecting. The charging station's connections are marked R, L and GUIDE.
2. Disconnect all connected wires and the power supply.
3. Connect all the wires and the power supply if there is no longer a risk of thunder. It is important that each wire is connected to the right place.

3 Installation

3.1 Presentation

This chapter contains information that is important to be aware of when planning the installation.

Before starting the installation make yourself familiar with what is included in the carton.

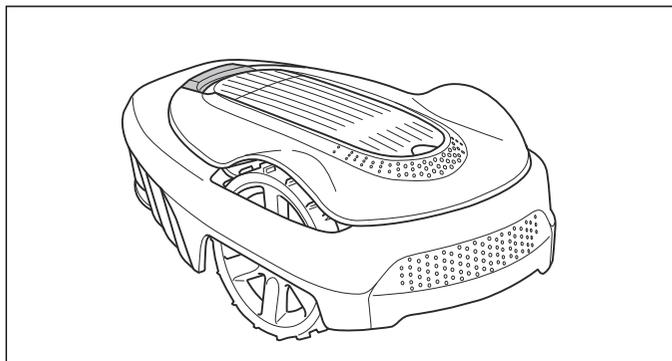
SILENO city / smart SILENO city	
Robotic lawnmower	✓
Charging station	✓
Power supply	✓
Loop wire, m	150 / 150
Low voltage cable	✓
Pegs, pcs	200 / 200
Connectors, pcs	5 / 5
Charging station screws, pcs	4 / 4
Allen key	✓
Measurement gauge	✓
Couplers, pcs	4 / 4
Operator's manual and Quick guide	✓
Cable markers	✓

smart SILENO city	
smart gateway	✓
smart gateway LAN-cable	✓
smart gateway power supply	✓

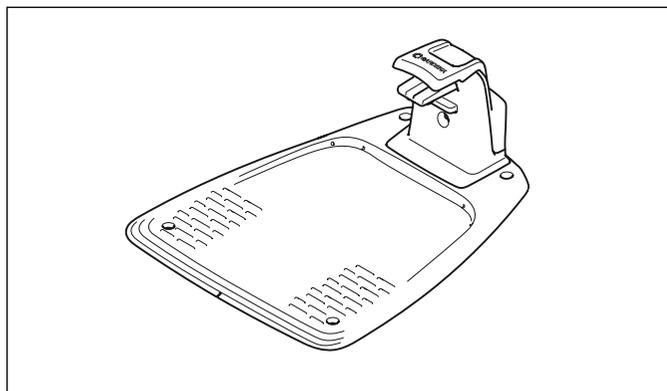
3.1.1 Main components for installation

The installation of the robotic lawnmower involves 4 main components:

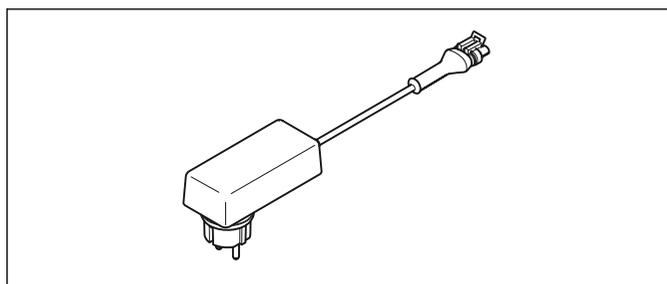
1. A robotic lawnmower that mows the lawn by essentially operating in a random pattern.



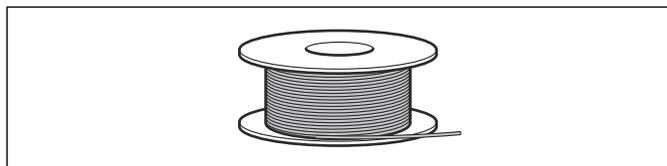
2. A charging station, to where the robotic lawnmower returns when the battery level becomes too low.



3. A power supply, which is connected to the charging station and a 100-240V wall socket. The power supply is connected to the wall socket and to the charging station using a 5 m / 16ft. long low voltage cable. Low voltage cables with 3 m / 10 ft., 10 m / 33 ft. and 20 m / 66 ft. length are available as optional accessories. No parts of the power supply must be changed or tampered with. For example the low voltage cable must not be shortened or extended.



4. Loop wire, which is laid around the edges of the lawn and around objects and plants that the robotic lawnmower must not run into. The loop wire is used both as a boundary wire and a guide wire. The maximum permitted length for the boundary loop is 300 m / 984 ft.



3.2 Preparations

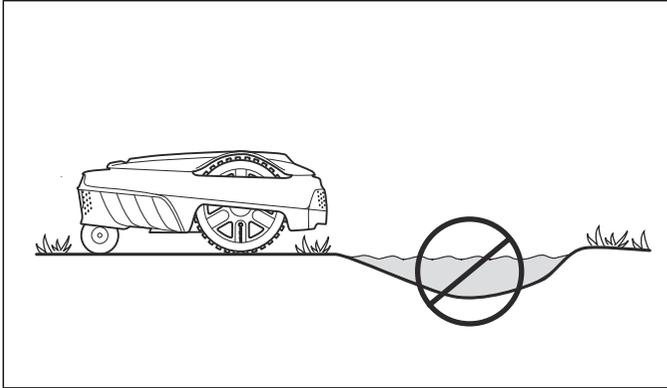
Read through this entire chapter before beginning the installation. How the installation is done also affects how well the robotic lawnmower works. It is therefore important to plan the installation carefully.

Planning is simplified if you make a sketch of the working area, including all obstacles. This makes it easier to see the ideal positions for the charging station, the boundary wire and the guide wire. Draw on the sketch where the boundary and guide wires should be routed.

Visit www.gardena.com for further descriptions and tips regarding installation.

1. If the grass in the working area is longer than 4 cm, mow it using a standard lawnmower. Collect the grass.

- Fill in holes and hollows to stop rainwater forming pools of water. The product may be damaged if it is operated in pools of water. See *Guarantee terms on page 53*.

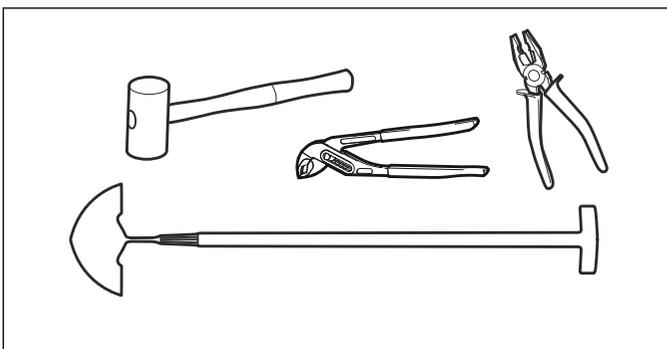


- Read carefully through all the steps before the installation.
- Check that all parts for the installation are included. See *Product overview on page 5*.
 - Robotic lawnmower
 - Charging station
 - Loop wire for boundary loop and guide wire
 - Power supply
 - Low voltage cable
 - Pegs
 - Connectors for the loop wire
 - Screws for the charging station
 - Measurement gauge
 - Couplers for the loop wire
 - Cable markers

3.2.1 Installation tools

During installation you will also need:

- Hammer/plastic mallet (to simplify putting the pegs in the ground).
- Combination pliers for cutting the boundary wire and pressing the connectors together.
- Polygrip (for pressing the couplers together).
- Edge cutter/straight spade if the boundary wire is to be buried.



3.3 Charging station

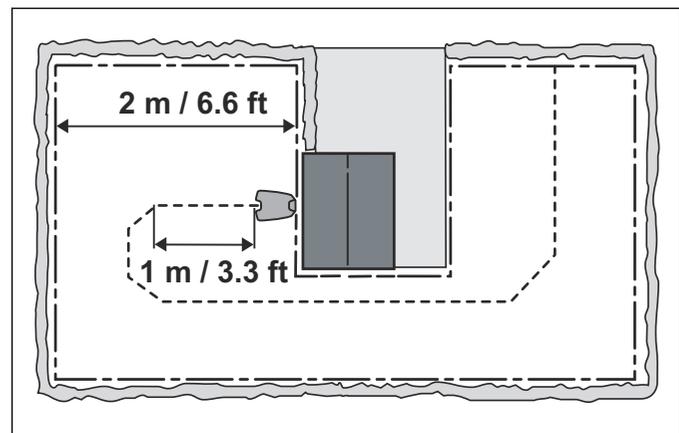
The charging station has 3 functions:

- To send control signals along the boundary wire.
- To send control signals in the guide wire so that the robotic lawnmower can find the charging station.
- To charge the robotic lawnmower battery.

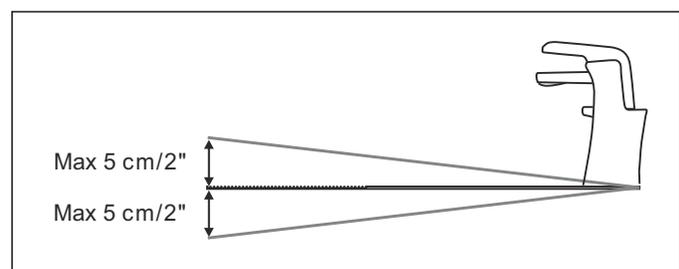
3.3.1 Best charging station location

Take the following aspects into consideration when identifying the best location for the charging station:

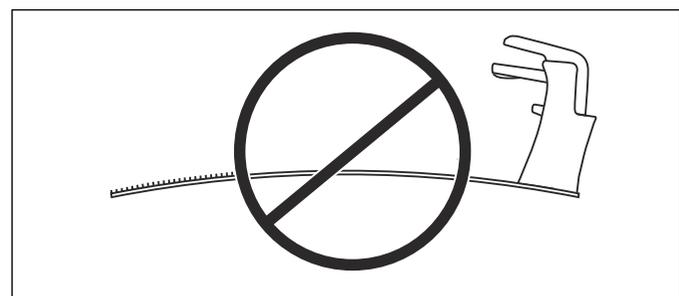
- Allow minimum 2 m of free space in front of the charging station.
- The positioning of the charging station is flexible. However, it is recommended that the boundary wire is not closer to itself (parallel) than 60 cm / 24 in. Otherwise the robotic lawnmower can have difficulties finding the charging station. See *Laying the boundary wire in towards the charging station on page 17*.
- It must be close to a wall socket. The supplied low voltage cable is 5 m long.
- A level surface free from sharp objects to place the charging station on.
- Protection from direct sunlight.
- Place it in the lower part of a working area that has a major slope.
- Possible requirement to keep the charging station out of sight for outsiders.



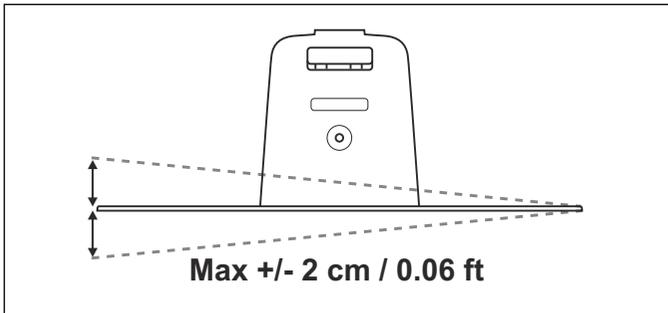
The charging station must be positioned on level ground. The front end of the charging station cannot be positioned higher or lower than the back end according to picture below.



The charging station must not be positioned in a way that can bend its base plate.

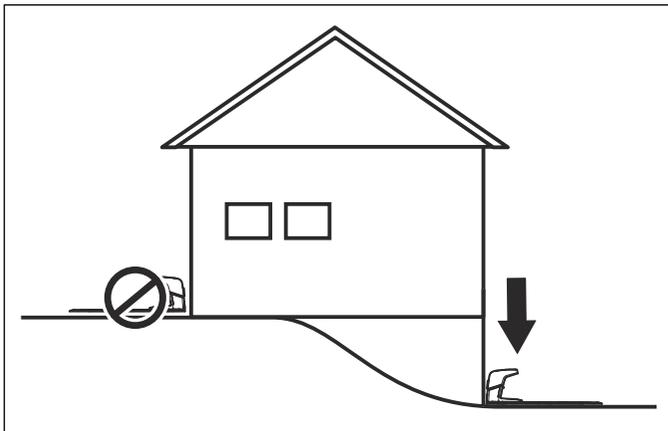


It is also important that the charging station is not bent sideways. Otherwise the robotic lawnmower might have difficulties docking.

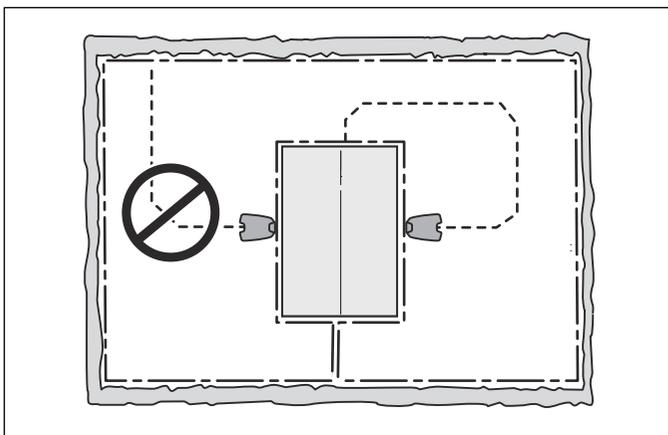


Note: Position the charging station on level ground so that the robotic lawnmower has optimal conditions for docking. It is essential that the charging plate is neither bent nor tilted in any direction.

If the installation is done in a working area with a steep slope, the charging station should be placed at the bottom of the slope. This makes it easier for the robotic lawnmower to follow the guide wire to the charging station.



The charging station should not be placed on an island as this limits the laying of the guide wire in an optimal way. If the charging station has to be installed on an island, the guide wire also has to be connected to the island. Read more about islands in the *Boundaries within the working area* on page 15.



Note: Correct placement of the charging station and the guide wire is important for the docking ability of the robotic lawnmower. Read more in *Laying the boundary*

wire in towards the charging station on page 17 and in Installation of the guide wire on page 18.

3.3.2 Connecting the power supply

Consider the following when planning where to place the power supply:

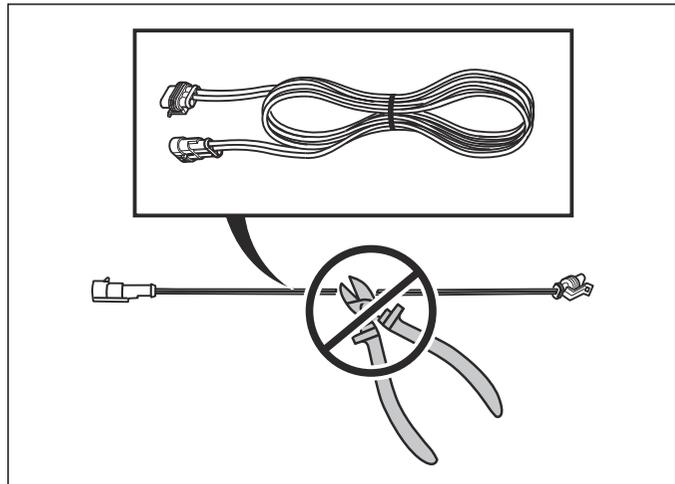
- Close to the charging station
- Protection from rain
- Protection from direct sunlight

The power supply must be placed where it is well ventilated and must be placed under a roof. If the power supply is connected to an electrical socket outdoors, this must be approved for outdoor use. It is recommended to use an earth fault-breaker (RCD) when connecting the power supply to the wall socket.

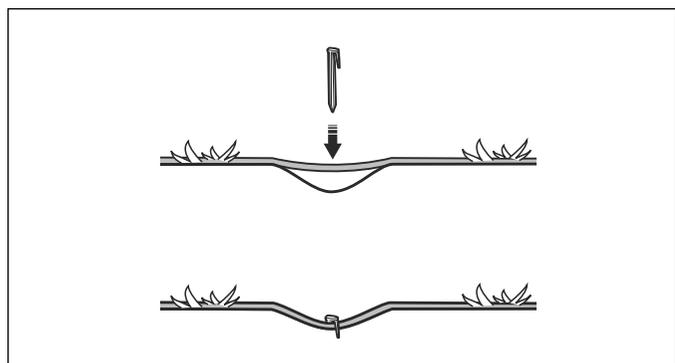


WARNING: Applicable to USA/Canada. If power supply is installed outdoors: Risk of electric shock. Install only to a covered Class A GFCI receptacle (RCD) that has an enclosure that is weatherproof with the attachment plug cap inserted or removed.

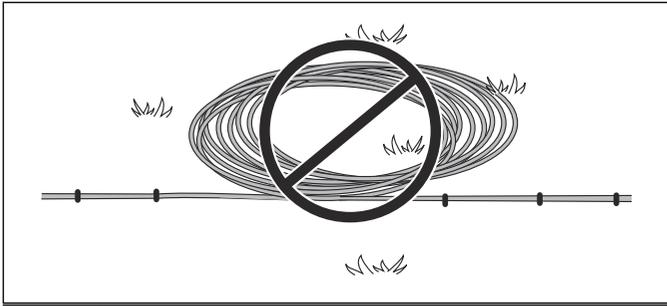
No parts of the power supply must be changed or tampered with. For example the low voltage cable must not be shortened or extended. Low voltage cables with 3 m, 10 m or 20 m length are available as optional accessories.



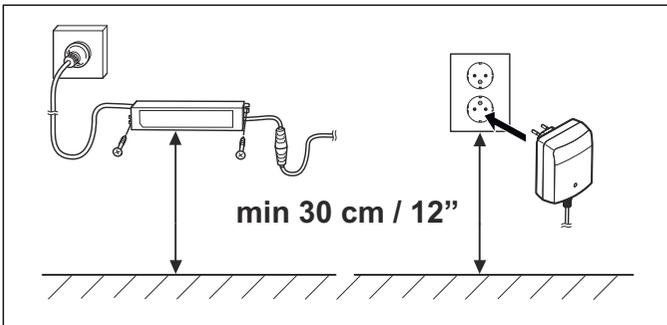
It is possible to let the low voltage cable cross the working area if it is stapled down or buried. The cutting height should be such that the blades can never come in contact with the low voltage cable.



The low voltage cable must never be stored in a coil or under the charging station's base plate as this can interfere with the signals from the charging station.



WARNING: Do not under any circumstances mount the power supply at a height where there is a risk it can be submerged in water (minimum 30 cm from the ground). It is not permitted to place the power supply on the ground.



The appearance of the power supply may differ depending on the market.

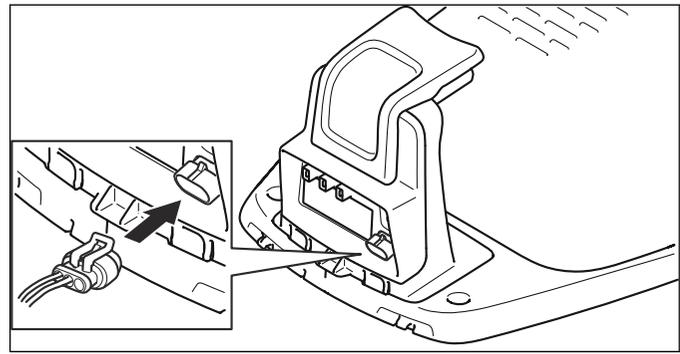
WARNING: No parts of the power supply must under any circumstances be changed or tampered with. The low voltage cable must not be shortened or extended.

WARNING: Use the plug to disconnect the charging station, for instance before cleaning the charging station or repairing the loop wire.

CAUTION: Place the low voltage cable and adjust the cutting height so that the blades can never come in contact with it.

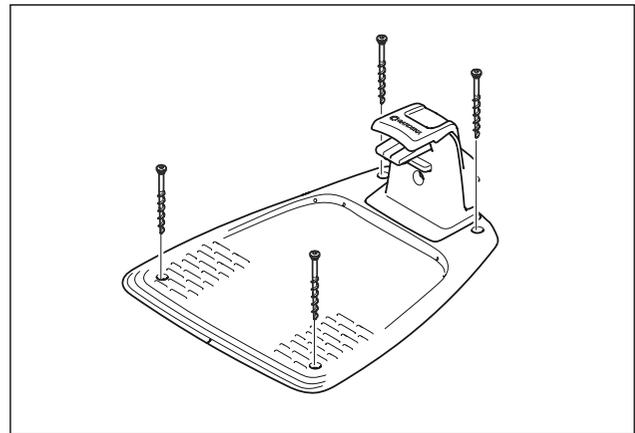
3.3.3 Installing and connecting the charging station

1. Position the charging station in a suitable spot. See *Best charging station location on page 11*.
2. Connect the low voltage cable to the charging station.



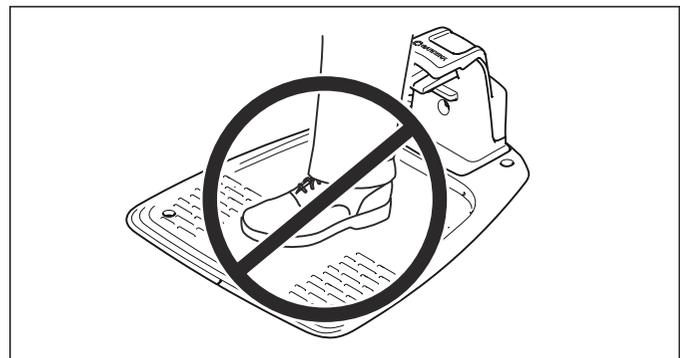
3. Connect the power supply's power cable to a 100-240V wall socket. If the power supply is connected to an electrical socket outdoors, this must be approved for outdoor use. See *Connecting the power supply on page 12*.
4. Attach the charging station to the ground using the supplied screws. Ensure the screws are screwed all the way down in the countersink.

Note: The guide wire must be laid and connected to the charging station before securing the charging station to the ground. See *Laying and connecting the guide wire on page 19*.



CAUTION: It is not permitted to make new holes in the charging station's plate. Only the existing holes may be used to secure it to the ground.

CAUTION: Do not tread or walk on the charging station's plate.



3.4 Charging the battery

When the charging station is connected, it is possible to charge the robotic lawnmower.

1. Place the robotic lawnmower in the charging station while the boundary and guide wires are being laid.
2. Press the **ON/OFF** button to turn the robotic lawnmower on.

If the battery is flat, it takes around 80 to 100 minutes to fully charge it.



WARNING: Only charge the robotic lawnmower using a charging station which is intended for it. Incorrect use may result in electric shock, overheating or leakage of corrosive liquid from the battery. In the event of leakage of electrolyte flush with water and seek medical help if it comes in contact with the eyes etc.

Note: The robotic lawnmower cannot be used before the installation is complete.

3.5 Boundary wire

The boundary wire can be installed in the following ways:

- Secure the wire to the ground with pegs.

Staple down the boundary wire if you want to make adjustments to the boundary loop during the first few weeks of operation. After a few weeks the grass will have grown over the wire making it no longer visible. Use a hammer/plastic mallet and pegs.

- Bury the wire.

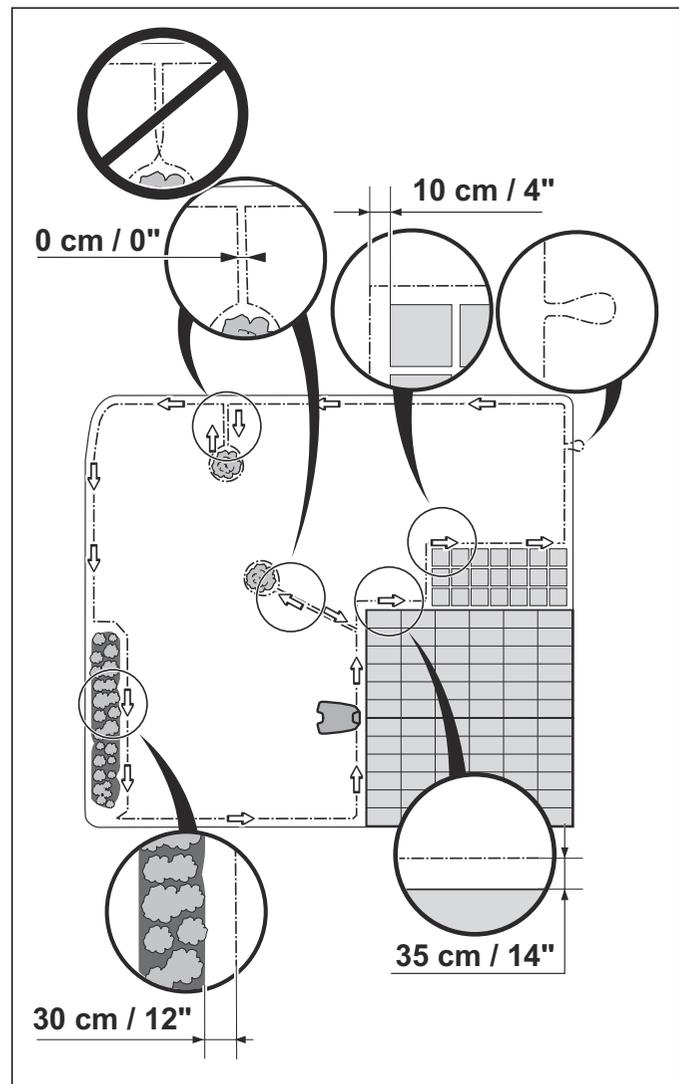
Bury the boundary wire if you want to dethatch or aerate the lawn. If necessary, both methods can be combined so one part of the boundary wire is stapled down and the other is buried. The wire can be buried for instance using an edge cutter or a straight spade. Make sure to lay the boundary wire at least 1 cm and a maximum of 20 cm in the ground.

3.5.1 Plan where to lay the boundary wire

The boundary wire must be laid so that:

- The wire forms a loop around the working area. Use original boundary wire. It is specially designed to resist dampness from the soil.
- The robotic lawnmower is never more than 15 m / ft. from the wire at any point in the working area.
- The wire is no more than 300 m / 984 ft. long.
- About 20 cm / 8 in. of extra wire is available to which the guide wire will be connected later. See *Laying the boundary wire on page 17.*

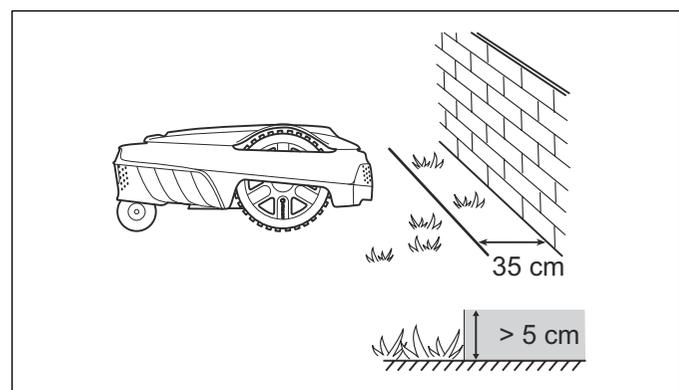
The illustration below shows how the boundary wire must be laid around the working area and around obstacles. Use the supplied measurement gauge to obtain the correct distance. See *Product overview on page 5.*



3.5.2 Working area boundaries

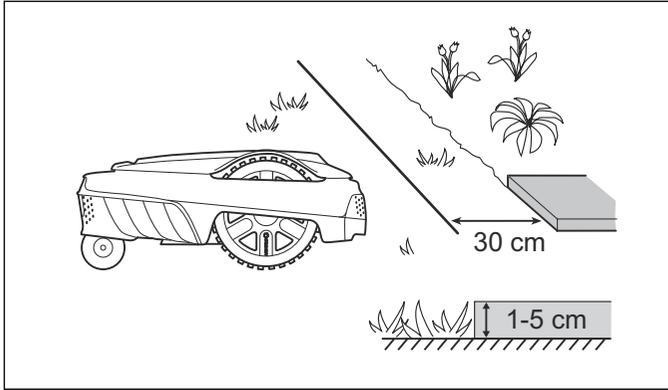
Depending on what the working area is adjacent to, the boundary wire must be laid at different distances from obstacles.

If a high obstacle (5 cm / 2 in. or more), for example a wall or fence, borders the working area, the boundary wire should be laid 35 cm / in. from the obstacle. This will prevent the robotic lawnmower from colliding with the obstacle and reduce body wear. About 20 cm / in. of the lawn around the fixed obstacle will not be mown.

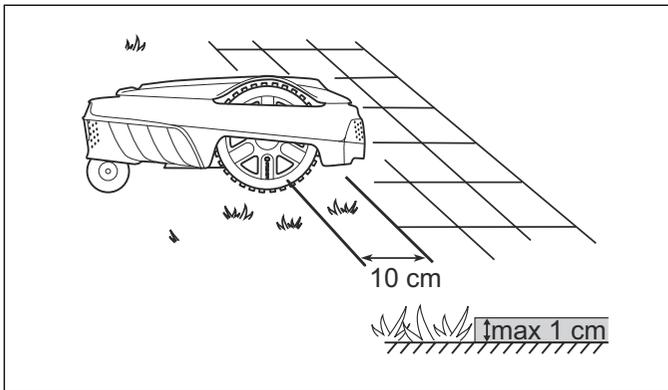


If the working area borders a small ditch, a flower bed or a small elevation, for example a low kerbstone (1-5 cm / in.), the boundary wire should be laid 30 cm / in. inside the working area. This prevents the wheels from driving into the ditch or up onto the kerbstone which might lead to excessive wear on the robotic lawnmower. About

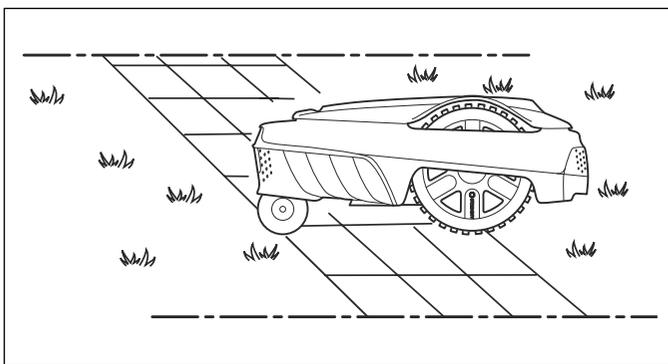
15 cm / in. of the lawn along the ditch/kerbstone will not be mown.



If the working area borders on a paving stone path or similar that is level with the lawn (+/- 1 cm / 0.4 in.), it is possible to allow the robotic lawnmower to run a little over the path. The boundary wire should then be laid 10 cm / in. from the edge of the path. All the grass along the side of the paving stone path will be cut.



When the working area is divided by a paving stone path that is level with the lawn, it is possible to allow the robotic lawnmower to run over the path. It can be an advantage to lay the boundary wire under the paving stones. The boundary wire can also be laid in the joint between the paving stones. Ensure that the tiles are in level with the lawn to avoid excessive wear on the robotic lawnmower.

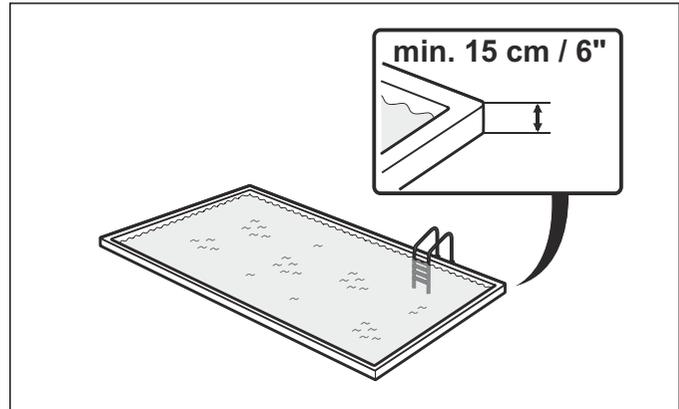


CAUTION: The robotic lawnmower must never run over gravel, mulch or similar material which can damage the blades.



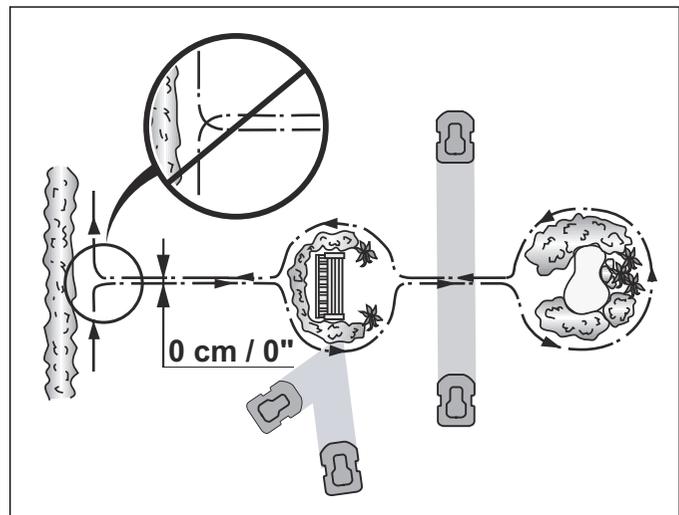
CAUTION: If the working area is adjacent to water bodies, slopes, precipices or a public road, the boundary wire must be supplemented with an edging or the like. It must then be at

least 15 cm / 6 in. in height. This will prevent the robotic lawnmower from ending up outside the working area under any circumstance.



3.5.3 Boundaries within the working area

Use the boundary wire to isolate areas inside the working area by creating islands around obstacles which cannot withstand a collision, for example flowerbeds, bushes and fountains. Lay the wire up to and around the area to be isolated, and then return it back along the same route. If pegs are used, the wire should be laid under the same pegs on the return route. When the boundary wires to and from the island are laid close together, the robotic lawnmower can drive over the wire.

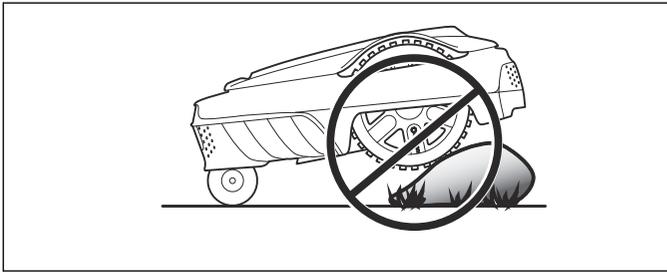


CAUTION: The boundary wire may not be crossed on its way to and from an island.

Obstacles that can withstand a collision, for example, trees or bushes taller than 15 cm / 6 in., do not need to be isolated with the boundary wire. The robotic lawnmower will turn around when it collides with this type of obstacle.

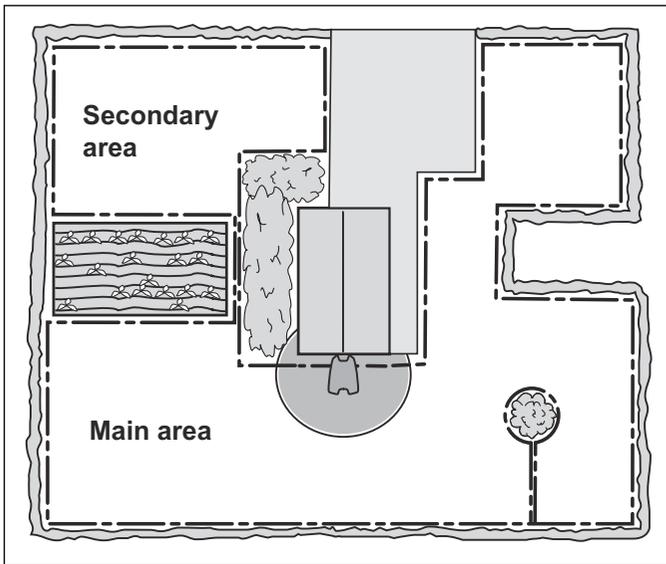
However, to achieve careful and silent operation, it is recommended to isolate all fixed objects in and around the working area.

Obstacles that slope slightly, for example stones or large trees with raised roots, must be isolated or removed. Otherwise the robotic lawnmower can slide up onto this kind of obstacle causing the blades to be damaged.



3.5.3.1 Secondary areas

If the working area consists of two areas which the robotic lawnmower has difficulty travelling between, it is recommended to set up a secondary area. Instances of this are slopes greater than 25% slopes or a passage that is narrower than 60 cm / 24in. Lay the boundary wire then around the secondary area so that it forms an island outside of the main area. The robotic lawnmower must be moved manually between the main and secondary area when the lawn in the secondary area has to be cut.



The *Secondary area* operating mode must be used as the robotic lawnmower cannot travel on its own from the secondary area to the charging station. See *Operating mode - 2nd area* on page 35. In this mode, the robotic lawnmower will never look for the charging station but will mow until the battery runs out. When the battery is flat, the robotic lawnmower will stop and the *Needs manual charging* message will appear in the display. Place the robotic lawnmower in the charging station to charge the battery. If the main area should be cut according to schedule after charging, operation mode *Main area* must be chosen and the **Start** button must be pressed.

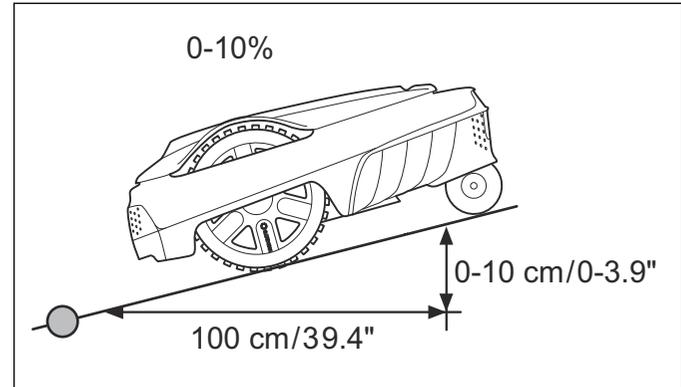
3.5.3.2 Passages when mowing

Long and narrow passages and areas narrower than 1.5 - 2 m / 3.2 - 6.5 ft. should be avoided. It is then a risk that the robotic lawnmower travels around in the passage or area for a period of time. The lawn will then look flattened. The narrowest possible passage for the robotic lawnmower is 60 cm / 24 in (between boundary wires).

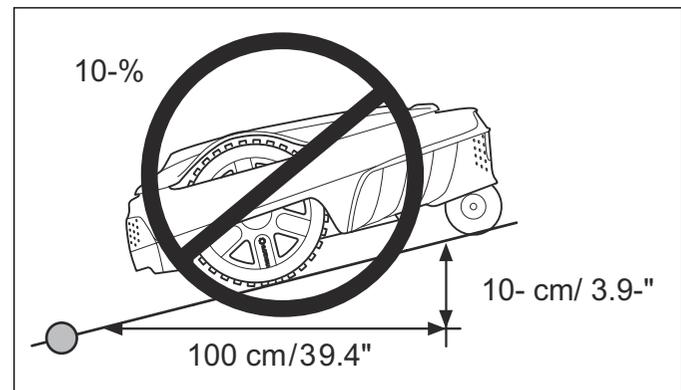
3.5.3.3 Slopes

The robotic lawnmower can operate in slopes. The maximum gradient is defined as percentage units (%)

and is calculated as difference in elevation in centimetres for every metre.



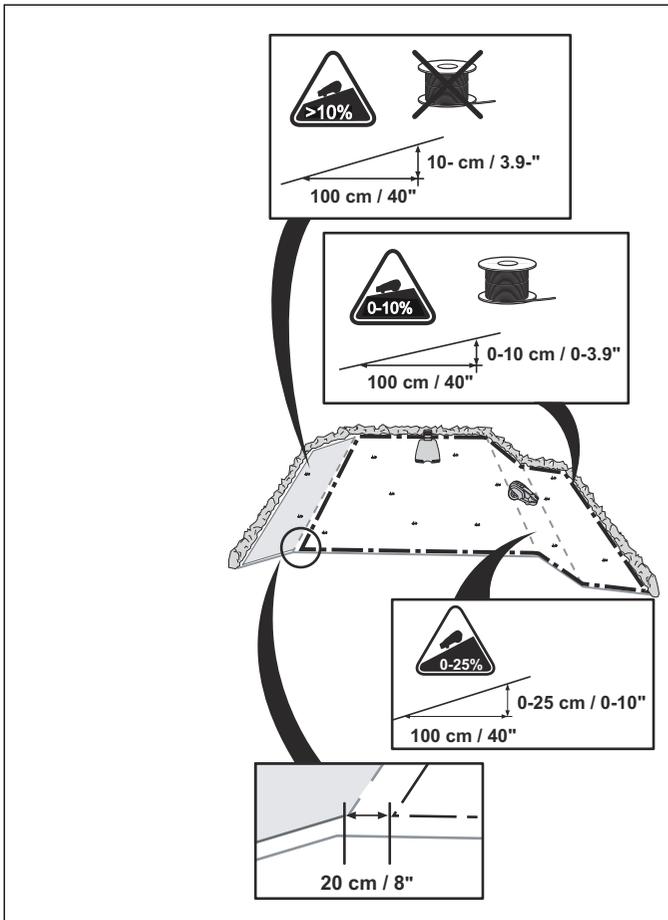
The boundary wire should not be laid across a slope that is steeper than 15%. There is a risk that the robotic lawnmower will find it difficult to turn there. The robotic lawnmower will then stop and the *Outside working area* fault message is displayed. The risk is at its greatest in damp weather conditions, as the wheels can slip on the wet grass.



However, the boundary wire can be laid across a slope steeper than 10% if there is an obstacle that the robotic lawnmower is allowed to collide with, for example, a fence or a dense hedge.

Inside the working area the robotic lawnmower can mow areas which slope up to 25%. Areas that slope more must be isolated with the boundary wire.

When a part of the working area's outer edge slopes more than 10%, the boundary wire must be laid about 20 cm in on the flat ground before the beginning of the slope.



3.5.4 Laying the boundary wire

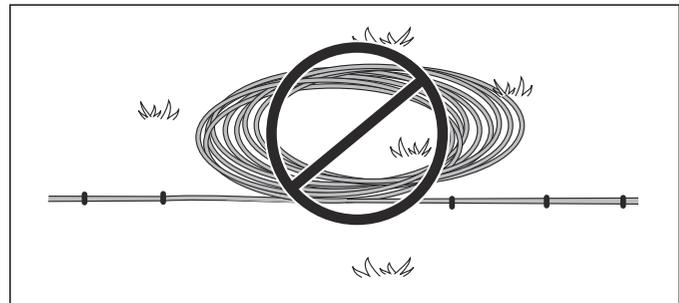
If you intend to staple down the boundary wire:

- Cut the grass very low with a standard lawnmower or a trimmer where the wire is to be laid. It will then be easier to lay the wire close to the ground and the risk of the robotic lawnmower cutting the wire or damaging the insulation of the wire is reduced.
- The boundary wire must lie close to the ground so as not to be cut before the grass roots have grown over it. Mowing the grass too low right after the installation can damage the wire insulation. Damage to the insulation may not cause disruptions until several weeks or months later. To avoid this, always select the maximum cutting height the first weeks after installation and then lower the height one step at a time every second week until the desired cutting height has been reached.
- Use a hammer to knock the pegs into the ground. Exercise care when knocking the pegs and make sure the wire is not under strain.

If the boundary wire is to be buried:

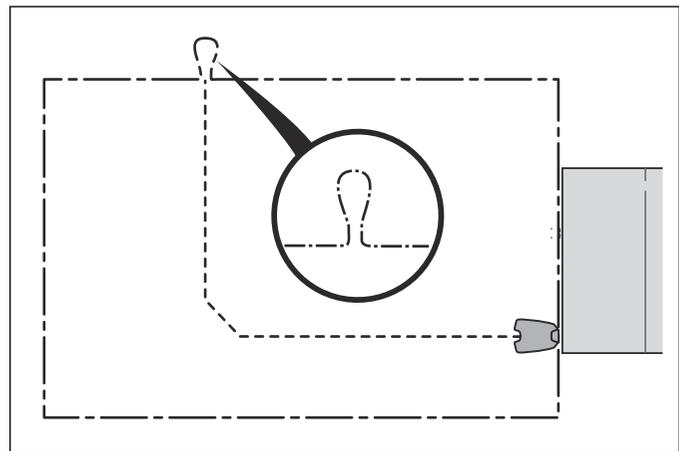
- Make sure to lay the boundary wire at a minimum of 1 cm / 0.4 in. and a maximum of 20 cm / 8 in. in the ground. The wire can be buried for instance using an edge cutter or a straight spade.

Note: Extra wire must not be placed in coils outside the boundary wire. This can disrupt the robotic lawnmower.



3.5.4.1 Eyelet for connecting the guide wire

To facilitate the connection of the guide wire to the boundary wire, it is recommended to create an eyelet with about 20 cm / 8 in. of extra boundary wire at the point where the guide wire will later be connected. It is a good idea to plan where the guide wire will be placed before laying out the boundary wire. See *Laying the boundary wire on page 17*.

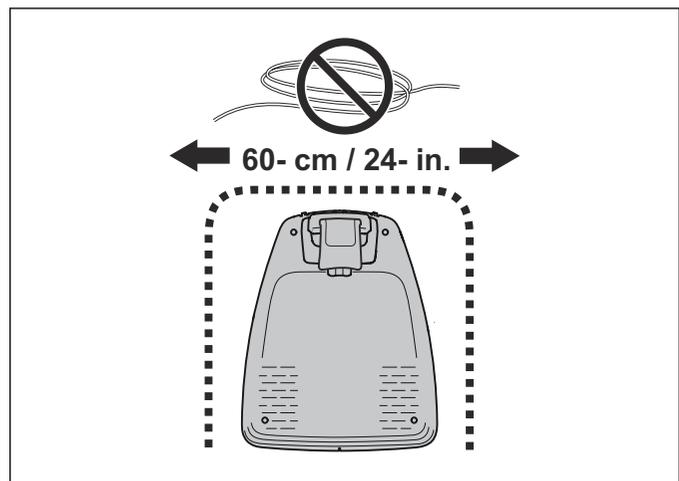


3.5.4.2 Laying the boundary wire in towards the charging station

The positioning of the charging station is flexible. However, it is recommended that the boundary wire is not closer to itself (parallel) than 60 cm / 24 in.



CAUTION: Do not place wire in coils, or the cable drum with loop wire, behind the charging station. This can interfere with the charging station signal and cause docking problems for the robotic lawnmower.



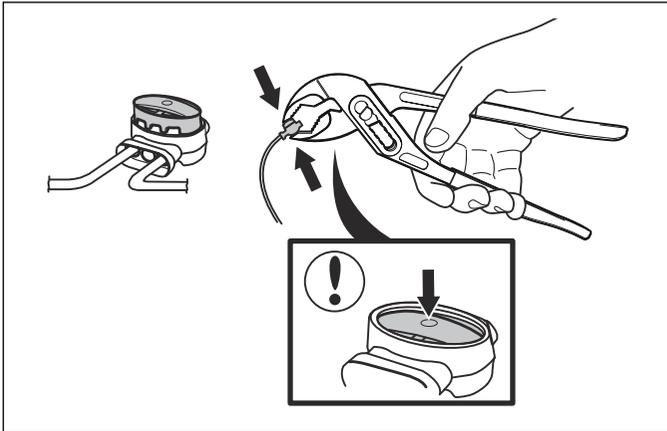
3.5.4.3 Splicing the boundary wire



CAUTION: Twinned cables, or a screw terminal block that is insulated with insulation tape are not satisfactory splices. Soil moisture will cause the wire to oxidise and after a time result in a broken circuit.

Use an original coupler if the boundary wire is not long enough and needs to be spliced. It is waterproof and gives a reliable electrical connection.

Insert both wire ends in the coupler. Check that the wires are fully inserted into the coupler so that the ends are visible through the transparent area on the other side of the coupler. Now press down the button on top of the coupler fully. Use a multigrip pliers to completely press down the button on the coupler.



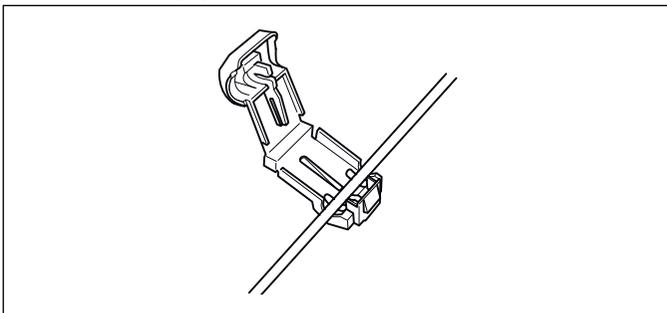
3.6 Connecting the boundary wire



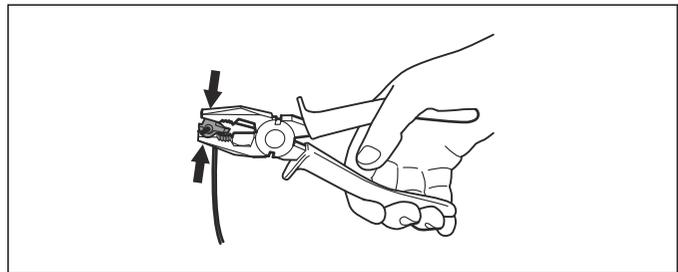
CAUTION: The boundary wire must not be crossed when connecting it to the charging station. The right hand wire end must be connected to the right hand pin on the charging station and the left hand wire end to the left pin.

Connect the boundary wire to the charging station:

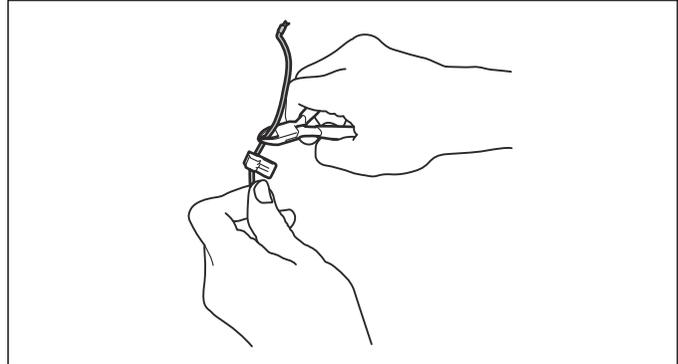
1. Open the connector and place the wire in the connector grip.



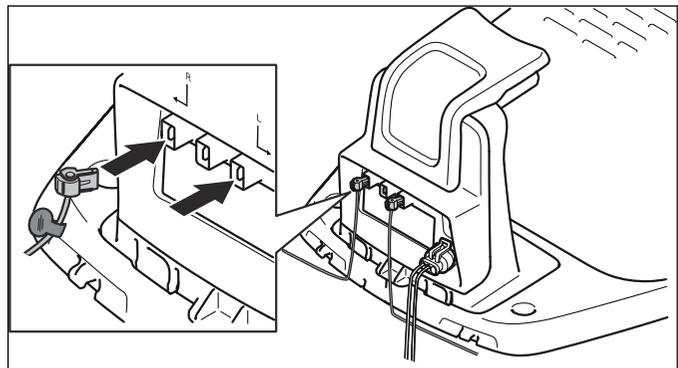
2. Press the connectors together using a pair of pliers. Press until you hear a click.



3. Cut off any surplus boundary wire. Cut 1-2 cm above each connector.



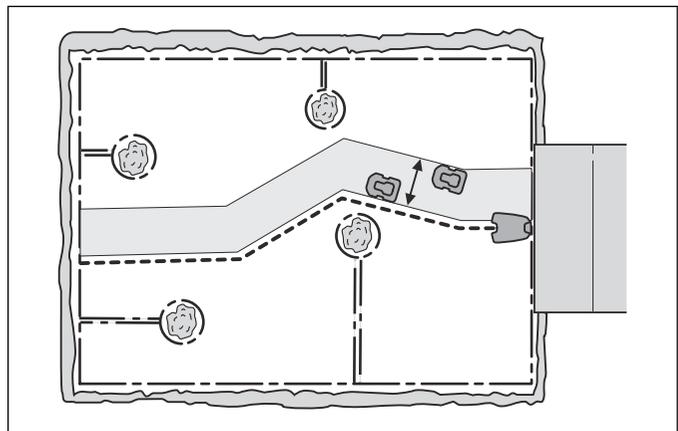
4. Press the connector onto the metal pins, marked L (left) and R (right), on the charging station.
5. Mark the wires with the accompanying cable markers. This makes it easier to connect the wires correctly when for instance the charging station has been stored indoors for the winter.



3.7 Installation of the guide wire

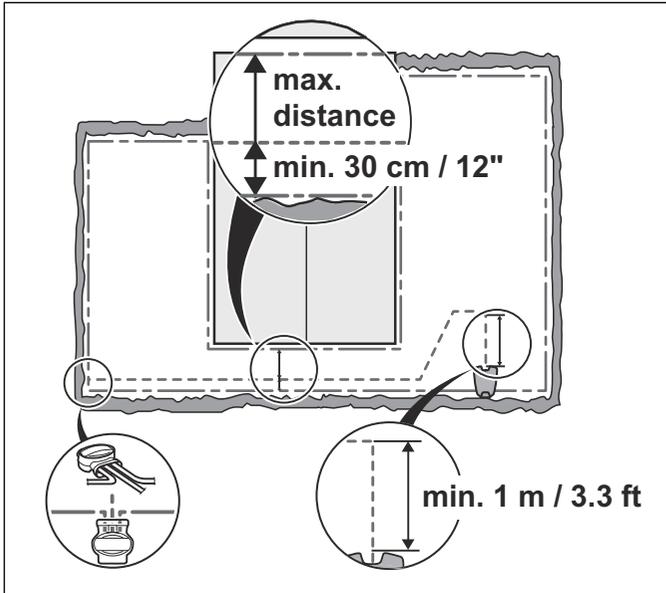
The guide wire is used by the robotic lawnmower to find its way back to the charging station but also to guide the robotic lawnmower to remote areas of the garden.

The same cable roll is used for both the boundary and guide wires. The guide wire, as the boundary wire, can be stapled to or buried in the ground.



The robotic lawnmower runs at varying distances from the guide wire to reduce the risk of tracks forming. The area beside the wire which the robotic lawnmower then uses is called the Corridor.

The robotic lawnmower always runs to the left of the guide wire as seen facing the charging station. Thus the corridor is to the left of the guide wire. When installing, it is therefore important to create as much free space as possible to the left of the guide wire, as seen facing the charging station.



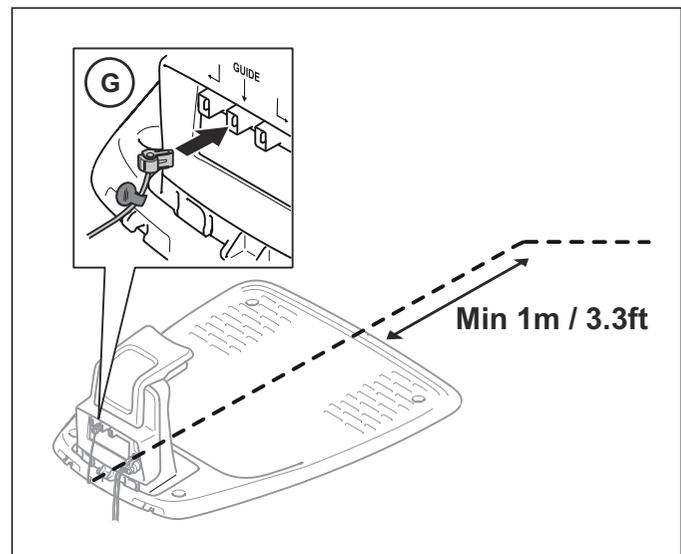
The guide wire, as the boundary wire, can be stapled to or buried in the ground.



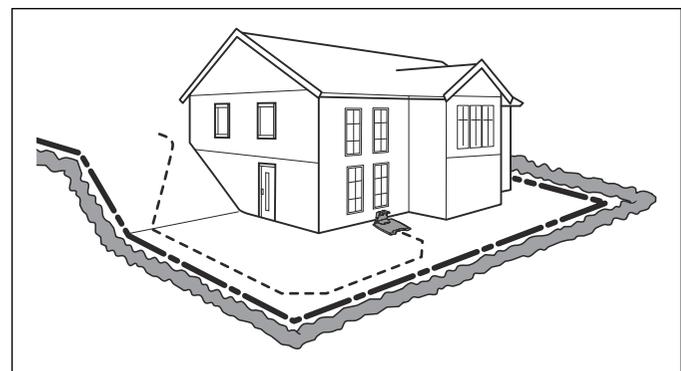
CAUTION: Make as much space as possible to the left of the guide wire (as seen facing the charging station). Also, it is not allowed to lay the guide wire closer than 30 cm from the boundary wire.

3.7.1 Laying and connecting the guide wire

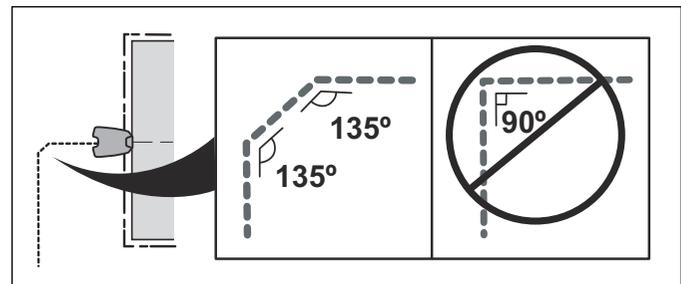
1. Before laying and connecting the guide wire, it is important to considerate the length of the guide wire, especially in large or complex installations. If the guide wire is longer than 150 m the robotic lawnmower can have difficulty following it. The current in the guide wire always goes to the left at the connection from the guide wire to the boundary loop.
2. Fit a connector to the guide wire in the same way as for the boundary wire in *Connecting the boundary wire on page 18*. Connect it to the contact pin on the charging station that is labelled GUIDE.
3. Mark the wires with the accompanying cable markers. This makes it easier to reconnect the wires correctly when for instance the charging station has been stored indoors for the winter.
4. Run the guide wire through the slot under the charging plate and then at least 1 m straight out from the front edge of the plate.



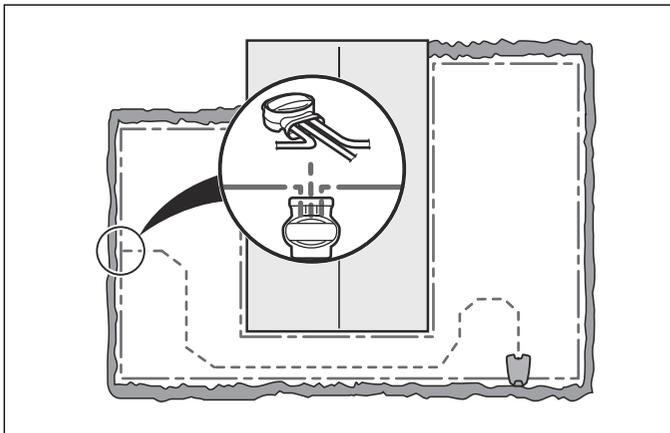
If the guide wire has to be installed on a slope, it is an advantage to lay the wire at an angle to the slope. This makes it easier for the robotic lawnmower to follow the guide wire on the slope.



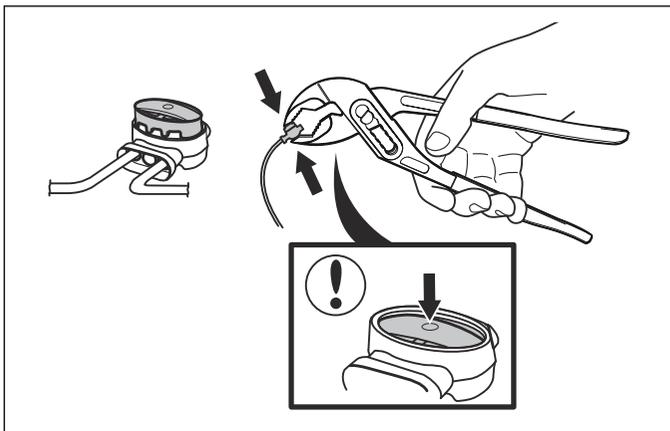
Avoid laying the wire at sharp angles. This can make it difficult for the robotic lawnmower to follow the guide wire.



5. Run the guide wire to the point on the boundary loop where the guide wire is to be connected.
6. Cut the boundary wire using for instance a pair of wire cutters. Connecting the guide wire is made easier if an eyelet has been made on the boundary wire as outlined in the previous description. See *Laying the boundary wire on page 17*.



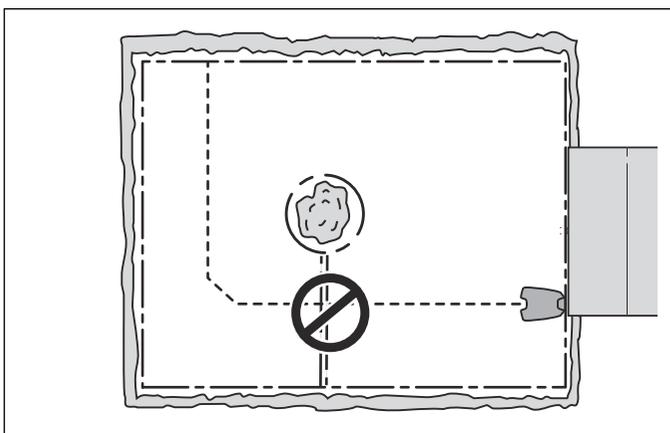
7. Connect the guide wire to the boundary wire using a coupler:
- Insert the boundary wire and guide wire in the coupler. Check that the wires are fully inserted into the coupler so that the ends are visible through the transparent area on the other side of the coupler.
 - Use a polygrip to completely compress the button on the coupler. It does not matter which holes are used to connect each wire.



8. Staple down or bury the splice in the lawn.

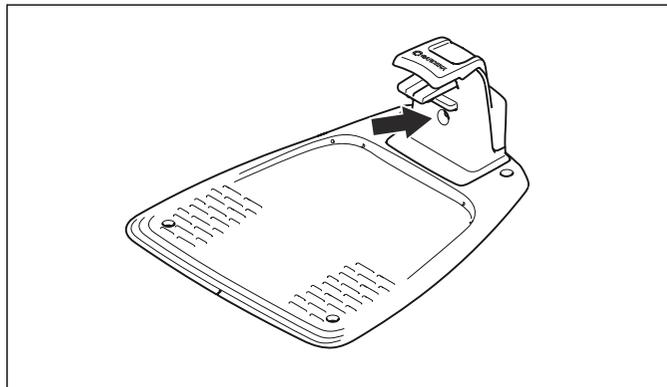


CAUTION: The guide wire may not cross the boundary wire, for instance a boundary wire that is laid out to an island.



3.8 Checking the installation

Check the loop signal by inspecting the indicator lamp on the charging station.



See *Indicator lamp in the charging station* on page 45 if the lamp does not indicate a solid or flashing green light.

3.9 First start-up and guide calibration

3.9.1 First start-up

When the robotic lawnmower is started for the first time (**ON/OFF** button), a start-up sequence in the robotic lawnmower's menu is carried out as well as an automatic calibration of the guide signal.

- Open the hatch.
- Press the **ON/OFF** button.

A start-up sequence begins when the robotic lawnmower is started for the first time. The following is requested:

- Language
- Country
- Date
- Time
- Selection and confirmation of personal PIN code. All combinations except 0000 are permitted.

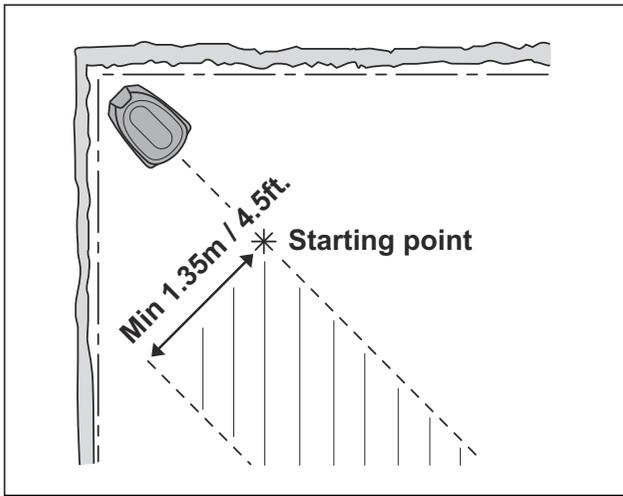
Note: Use the *MEMO* page at the beginning of the manual to make a note of the PIN code.

- Place the robotic lawnmower in the charging station and press the **Start** button.

3.9.2 Guide calibration

- The robotic lawnmower drives out of the charging station and straddles the guide wire to the starting point (default distance 60 cm / 2 ft.), where the calibration process begins. The maximum distance from the charging station to the starting point is 300 cm / 9.8 ft. The calibration process sets as wide guide corridor as possible to reduce the risk of tracks forming on the lawn. See *Starting point* on page 27.

Note: The robotic lawnmower always runs to the left of the guide wire (as seen facing the charging station). For the widest possible guide corridor, make sure that the distance from the starting point to the boundary wire is minimum 1.35 m / 4.5 ft. (perpendicular to the guide wire). If the distance on the left side of the starting point is less than 0.6 m / 2 ft. the calibration process is interrupted.



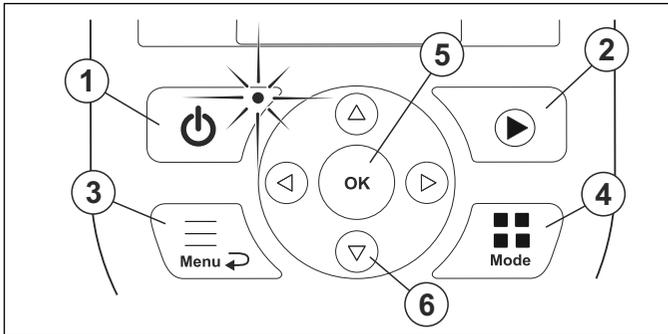
- When the guide calibration is completed, the robotic lawnmower follows the guide wire and then starts mowing.

3.10 Control panel

All commands and settings for the robotic lawnmower are done on the control panel. The control panel consists of a display and a keypad. All information is shown on the display and all input is done using the buttons.

3.10.1 Keypad

The keypad consists of 6 groups of buttons:



- The **ON/OFF** button is used to turn the robotic lawnmower **ON/OFF**. The indicator lamp on the **ON/OFF** button is an important status indicator. See *The indicator lamp on page 35*.
- The **Start** button is used to start the operation of the robotic lawnmower.
- The **Menu** button is used to go to the main menu.
Note: The **Menu** button is also used as a **Back** button, that is, when moving back up in the menu lists.
- The **Mode** button is used to choose operating mode, for example, *Main area* or *Park*.
- The **OK** button is used to confirm the chosen settings in the menus.
- The **arrow keys** are used to navigate in the menu. The **up/down arrow keys** are also used to enter digits, for example, PIN code, time and date



WARNING: It is only safe to carry out inspection or maintenance on the robotic lawnmower when the robotic lawnmower is disabled. The robotic

lawnmower is disabled when the lamp on the **ON/OFF** button is not lit.

3.10.2 Display

When the **STOP** button is pressed and the hatch is opened, the display shows the following information:



- Operating information, for example, *MOWING*, *PARKED*, *SEARCHING* or *SCHEDULE*. If the robotic lawnmower is not in any specific operating mode, the operating information *READY* is displayed.
- Date and time.

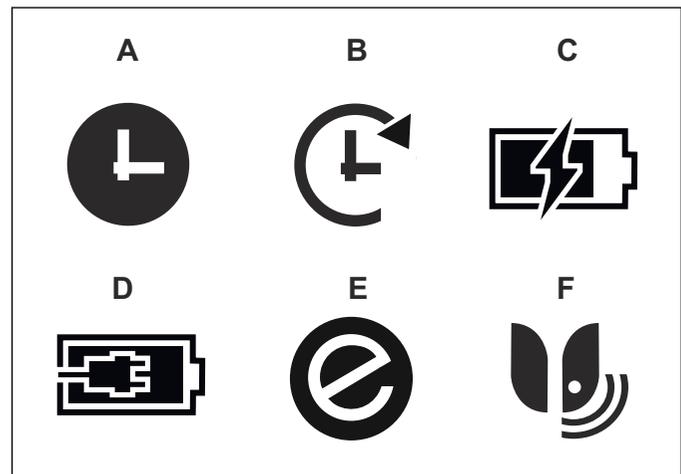
3.10.2.1 Symbols shown on the display

The clock symbol (A) indicates when the mower is not allowed to mow due to a schedule setting. If the operation mode *Override schedule* is chosen, symbol (B) is shown.

The battery status shows the remaining battery charge. If the robotic lawnmower is loading, a flash is shown over the battery symbol (C). If the robotic lawnmower is placed in the charging station without charging, (D) is shown.

The ECO symbol (E) is displayed if the robotic lawnmower is set in *ECO mode*. See *ECO mode on page 28*.

The smart system symbol (F) is displayed if the robotic lawnmower is included to a smart system.



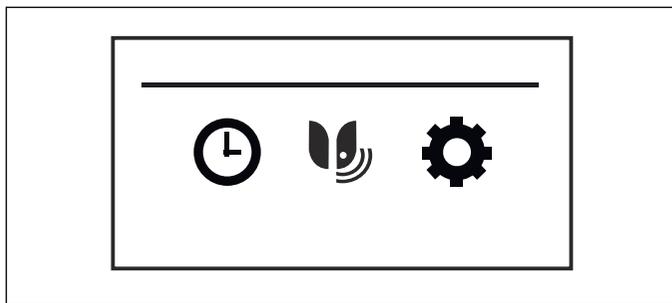
3.11 Menu structure

The robotic lawnmower has a main menu with a number of submenus under each option. All settings are done in the submenus.

The main menu has the following structure:

- Schedule*

- *smart system* (only for smart SILENO city)
- *Settings*



3.11.1 Main menu



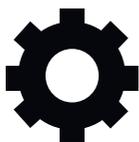
Schedule

The schedule function is an ideal tool to control which periods the robotic lawnmower should not mow, for example when children are playing in the garden. The scheduling wizard is a quick tool to find suitable schedule settings for the robotic lawnmower. See *Scheduling wizard* on page 22



smart system

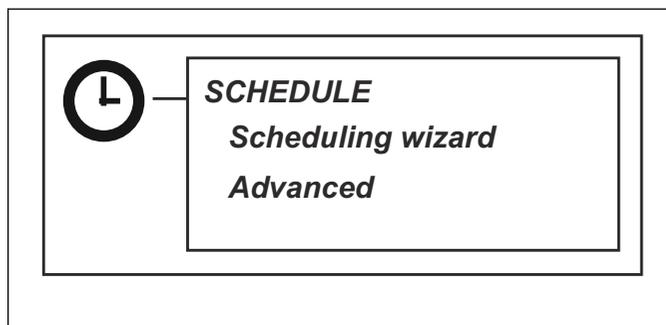
Only for smart SILENO city
GARDENA smart system enables wireless interaction between the robotic lawnmower and other devices in GARDENA smart system, such as water controls and sensors. In this menu, the robotic lawnmower can be included in, or excluded from, the smart system. It is also possible to check the wireless connection status to smart system. See *smart system* on page 24.



Settings

For many working areas there is no need to alter the factory default settings, but depending on the lawn complexity the mowing result can be improved by making manual settings. The functions in the settings menu are used to customize the installation. In the settings menu, it is also possible to make changes to the general settings of the robotic lawnmower, such as date and time. The *Settings* menu also includes settings related to security, and the connection between the robotic lawnmower and the charging station. See *Settings* on page 25.

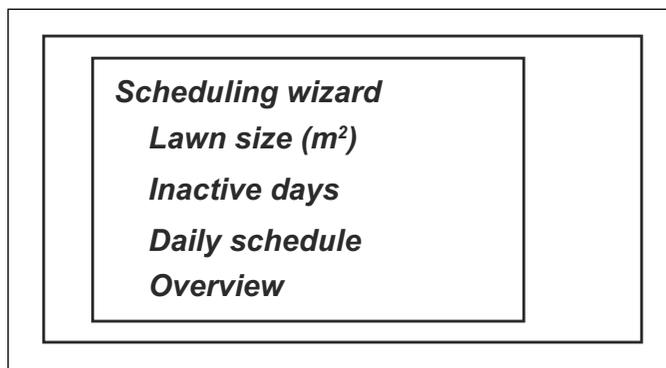
3.12 Schedule



The lawn should not be cut too often to obtain the best mowing result. When the robotic lawnmower is allowed to mow too much, the lawn may appear flattened. Besides, the robotic lawnmower is subjected to unnecessary wear. If the working area is less than the robotic lawnmower's area capacity, the quality of the grass can be further improved if it is cut every other day instead of a few hours every day. In addition, the grass benefits from resting completely during at least a three-day period once a month.

The schedule function is also an ideal way to control which periods the robotic lawnmower should not mow, for example, when the children are playing in the garden.

3.12.1 Scheduling wizard

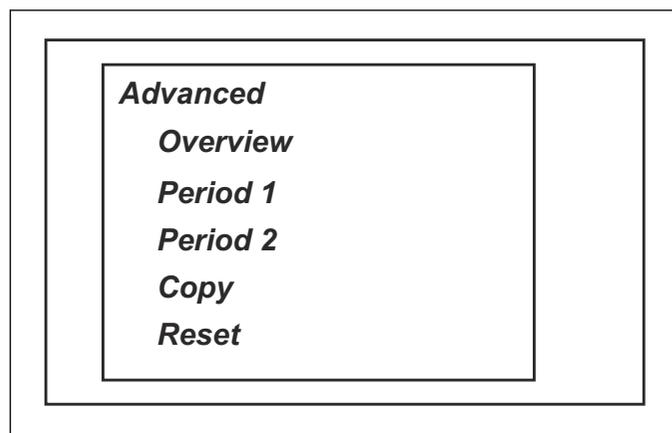


The scheduling wizard is a quick tool to find suitable schedule settings for your lawn.

1. Enter your estimated lawn size. It is not possible to enter a larger lawn size than the maximum working capacity. See *Technical data* on page 51
2. Confirm the lawn size by pressing the **OK** button. By entering your lawn size the wizard suggests either a suitable daily schedule (go to step 4) or need input for inactive days.
3. Choose what day(s) the robotic lawnmower should be inactive. Use the up/down arrow keys to shift between days.
4. Confirm the chosen inactive day(s) by pressing the **OK** button.
5. The wizard suggests a daily schedule for the active days. If you want to move the schedule interval to earlier or later in the day then press the **arrow** keys up or down.
6. Confirm the daily schedule by pressing the **OK** button. An overview of the daily schedule is presented. Press **OK** button to go back to main menu.

If you want to change the schedule settings for individual work days use the *Schedule - Advanced* menu.

3.12.2 Advanced



The operating hours and days can be seen in an overview on the robotic lawnmower's display. Active mowing per day is illustrated by a colored bar. The rest of the time, the robotic lawnmower is parked in the charging station.

If the working area is less than maximum capacity then the schedule should be used to minimize wear on grass and lawnmower. When setting the schedule, calculate that the robotic lawnmower mows about the number of square meters per hour and day listed in table Work capacity. See *To set the schedule on page 36*.

3.12.3 Schedule suggestions

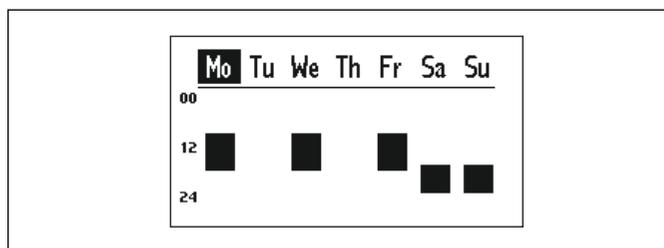
The scheduling wizard is an easy way to find a suitable schedule for the size of the lawn. However, if there is a need to customize the schedule settings this is done in the *Schedule - Advanced* menu. Each robotic lawnmower has a maximum working capacity (m²) which cannot be exceeded. The schedule suggestions below therefore only applies up to the maximum working capacity. For some work areas 7 work days are needed. Below table with schedule suggestions is applicable to SILENO city (for 500 m²). The suggestions of time interval are rounded to the next half hour.

Work area	Work days per week	Work hours per day	Suggestion of time interval
150 m ²	5	5	08:00 - 13:00
	7	3.5	08:00 - 11:30
250 m ²	5	8	08:00 - 16:00
	7	5.5	08:00 - 13:30
350 m ²	5	11	08:00 - 19:00
	7	8	08:00 - 16:00
400 m ²	7	9	08:00 - 17:00
450 m ²	7	10	08:00 - 18:00
500 m ²	7	11	08:00 - 19:00

3.12.4 Edit day

First select the day to edit from the Overview screen using the left/right **arrow keys** followed by **OK**.

2 time intervals per day can be entered. To enter an interval for *Period 1*, first make sure that the check box next to *Period 1* is checked. To check/uncheck select the check box and press **OK**. Enter the time using the up/down arrow keys.

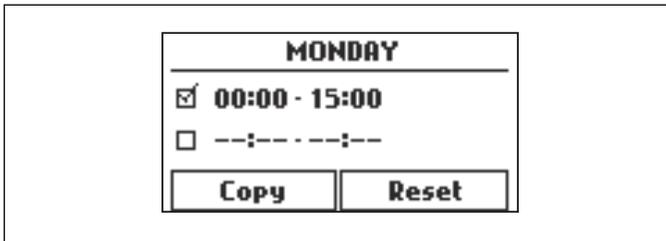


The table below provides suggestions for different schedule settings depending on the size of the lawn. The work hours per day should be seen as indicative. It may need to be adjusted to suit the garden and for example grass quality and growth during the season. Use the table as follows:

- Find a work area that closest matches the size of the lawn.
- Select an appropriate amount of work days.
- Work hours per day shows how many hours a day the robotic lawnmower will be allowed to work for the selected amount of work days.
- Suggested time interval shows a time interval that corresponds to the required work hours per day.

It is possible to configure 2 work periods a day. There can be unique work periods in each day, but it is also possible to copy the current day's work period to all the other days.

Use the right arrow key to move to *Period 2*. *Period 2* is entered the same way as *Period 1*. Two intervals can be useful for enabling the lawn for other activities during certain hours, for example by entering *Period 1*: 09:00-11:00 and *Period 2*: 21:00-24:00. The robotic lawnmower will then be parked in the charging station between 11:00 and 21:00.



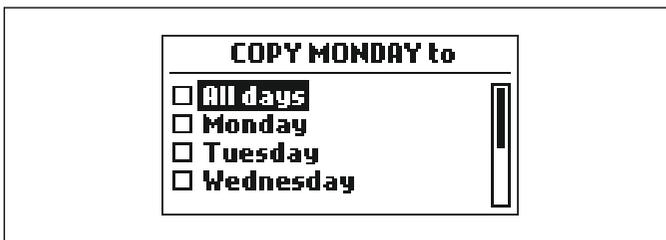
To disable mowing a whole day, uncheck both periods.

To return to the Schedule overview, press the **Menu** button.

3.12.5 Copy

Use this function to copy the current day settings to other days.

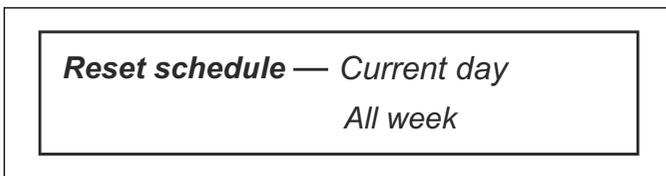
Mark *Copy* by using the **arrow keys** and press **OK**. Then use the up and down **arrow keys** to move the cursor between days. The times will be copied to the days that are marked with **OK**.



To return to the Schedule overview, press the **Menu** button.

3.12.6 Reset

This function resets the schedule to the factory setting, where the robotic lawnmower is allowed to operate according to the wizard settings (maximum working capacity).



3.12.6.1 Current day

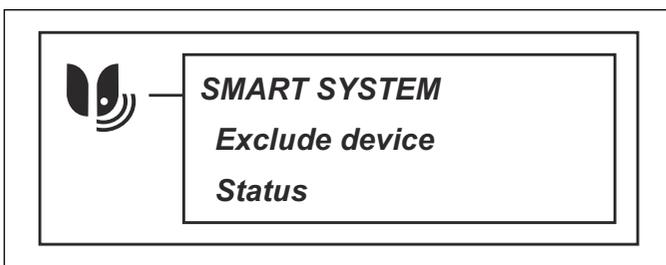
This resets the day that is selected in the tab system.

3.12.6.2 All week

This resets all days in the week.

3.13 smart system

Only for smart SILENO city.



The GARDENA smart system makes it possible with wireless interaction between your smart robotic lawnmower and other GARDENA smart system devices, such as smart Water Control and smart Sensor.

In this menu you can:

- enable your smart robotic lawnmower to include with or exclude from the GARDENA smart system app.
- check the status of the wireless connection to the smart system.

Note: The inclusion sequence might take several minutes. Once the inclusion has succeeded you will automatically return to the mower start screen. If the inclusion by any reason fails, try again.

3.13.1 Installation

Make sure that the smart robotic lawnmower is fully installed before you include it into the GARDENA smart system app. See *Installation on page 10*. It is important to plan the installation carefully.

3.13.2 Activate inclusion mode

In order to include your smart robotic lawnmower into the GARDENA smart system app:

1. Select the smart system icon from the main menu in the robotic lawnmower and press **OK**. The option *Activate Inclusion Mode* appears in the display.
2. Select *Yes* by pressing the right **arrow key** and then press **OK**.
3. Enter the pin code by using the up/down **arrow keys** and press **OK**.
4. The inclusion code is presented in the robotic lawnmower's display.

Note: The robotic lawnmower can only be shown as a device in the smart system app if it first has been included from the robotic lawnmower.

3.13.3 Inclusion in the App

The inclusion of all GARDENA smart devices takes place over the smart system app. The cost-free GARDENA smart system app can be downloaded from App Store (Apple) or Google Play (Android). Open the app and register as a user. Log in and choose *Include device* from the start page in the app. Continue the inclusion by following the instructions in the app. For the inclusion, a smart gateway connected to the internet is also needed.

Note: Carry out this step only after the robotic lawnmower installation has been completed.

3.13.4 Disabled menus

As soon as the smart robotic lawnmower is part of the smart system, some menus in the robotic lawnmower will be disabled. You can still see all of the settings in the robotic lawnmower but some can only be changed with the GARDENA smart system app. The following settings will be blocked in the menu selection of the smart robotic lawnmower:

- Schedule
- Time & Date
- Language

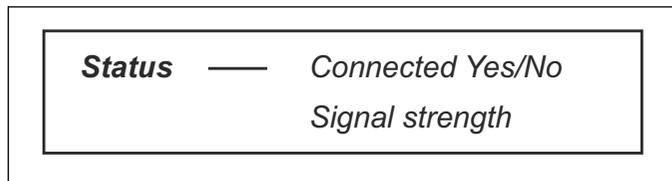
- Country

3.13.5 Exclude device

To remove the wireless connection between the robotic mower and smart system, select the *Exclude device* option in the robotic lawnmower menu. If you confirm to exclude the device, there will be no communication between the robotic lawnmower and other smart system devices.

Note: The robotic lawnmower must be manually deleted from the list of products in the GARDENA smart system app.

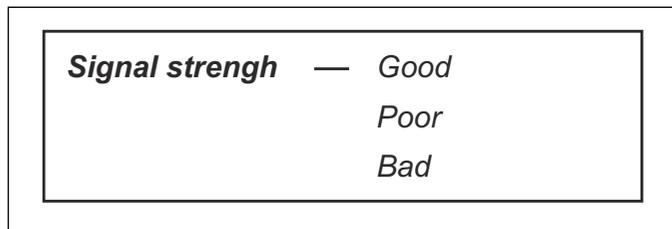
3.13.6 Status



3.13.6.1 Connected Yes/No

As soon as the robotic mower is connected to smart system gateway, you can check the connection status from this menu. The status is either connected (Yes) or not connected (No).

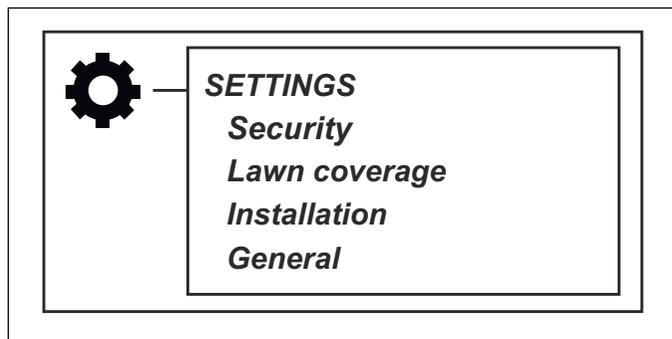
3.13.6.2 Signal strength



The signal quality between the robotic mower and the Gateway can be either *Good*, *Poor* or *Bad*. The robotic mower charging station should preferably be placed on a garden location with *Signal strength - Good*, for best smart system performance.

3.14 Settings

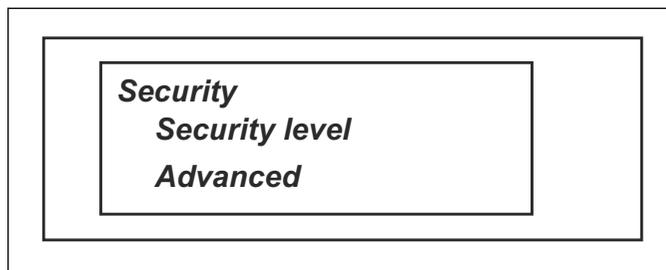
This selection allows you to carry out changes to the security, customize the installation and change general settings like time and date.



3.14.1 Security

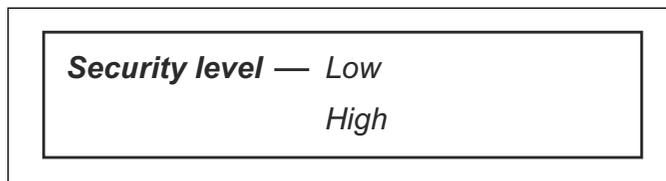
Through this selection, settings relating to security and the connection between the robotic lawnmower and the charging station can be made. To go into the security

menu first enter the PIN code by using the up/down arrow keys and press OK.



3.14.1.1 Security level

There are 2 security levels to choose from.



When starting the robotic lawnmower (**ON/OFF** button), both *Low* and *High* security prohibits access to the robotic lawnmower if the PIN code is unknown. If the wrong PIN code is entered 5 times in succession the robotic lawnmower is blocked for a time. The blockage time is extended for every new incorrect attempt.

Function	Low	High
Time lock	X	X
PIN request		X

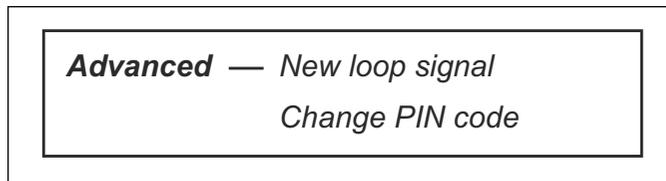
Time lock

This function means that the robotic lawnmower cannot be started after 30 days without first entering the correct PIN code. When the 30 days has passed the robotic lawnmower will continue to mow as normal, but the *Enter PIN code* message appears the next time **STOP** is pressed. Enter the PIN code and press **OK**.

PIN request

This function means that the robotic lawnmower requests a PIN code if the robotic lawnmower is in standby and has the security setting *High*. Standby (flashing indicator lamp) means that the operator must press the **ON/OFF** button to make the robotic lawnmower active again. The correct PIN code must be entered before it is possible to operate the robotic lawnmower.

3.14.1.2 Advanced



New loop signal

The loop signal is randomly selected to create a unique link between the robotic lawnmower and the charging station. In rare cases, there may be a need to generate a new signal, for instance if two adjacent installations have a very similar signal.

1. Place the robotic lawnmower in the charging station.

2. Select *New loop signal* in the menu.
3. Press **OK** and await confirmation that the loop signal has been generated. This normally takes about 10 seconds.

Change PIN code

1. Enter the current PIN code by using the up/down arrow keys and press **OK**.
2. Enter the new PIN code and press **OK**.
3. Confirm by entering the same code again and press **OK**.

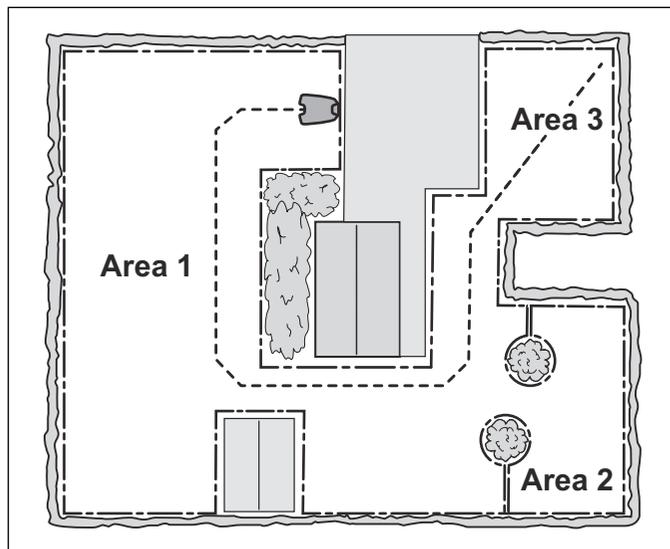
When the PIN code is changed, the message *PIN code changed* appears in the display. Make a note of the new PIN code on the designated line in Memo. See *Introduction on page 3*.

3.14.2 Lawn coverage

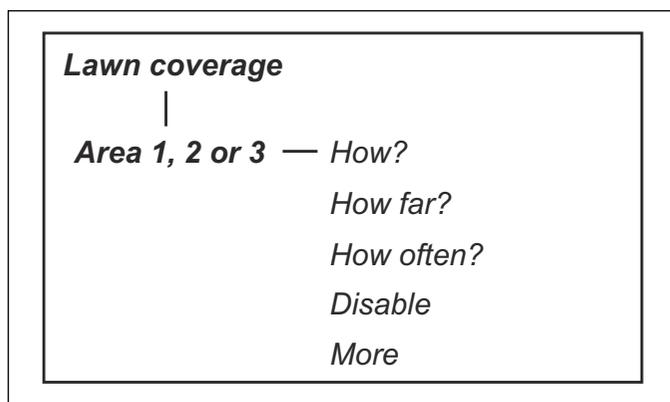
This menu function is used to steer the robotic lawnmower to remote parts of a working area. In complex gardens with for instance many areas which are joined by narrow passages, the mowing result can be much improved by changing settings.

Note: The lawn coverage function is enabled after a successful guide calibration. See *Guide calibration on page 20*.

Up to 3 remote areas can be set. Select an area using the left and right **arrow keys** followed by **OK**.



A number of unique selections are required to allow the robotic lawnmower to reach the remote area.



The factory settings allow the robotic lawnmower to follow the guide wire 99 m in 20% of the times it leaves the charging station. If the guide wire in reality is less than 99 m the robotic lawnmower will follow it to the point where the guide wire is connected to the boundary wire.

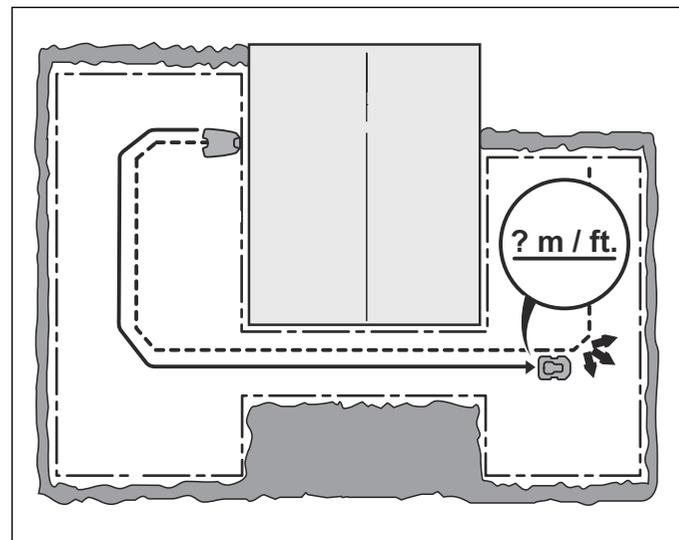
3.14.2.1 Area 1, 2 or 3 > How?

The robotic lawnmower uses the Guide to reach Area 1, 2 or 3. If all areas will be used it is therefore important to consider the optimal placement of the charging station. The Guide needs to pass all areas but at the same time not exceed maximum length of guide wire.

3.14.2.2 Area 1, 2 or 3 > How far?

The robotic lawnmower stops following the guide wire and starts mowing at a specified distance from the charging station. Up to 3 different distances can be set.

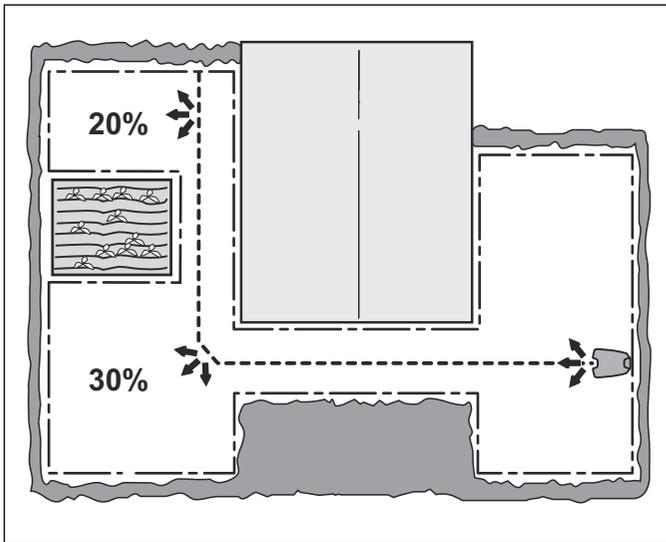
Tip! Use the *Test* function (*Area 1, 2 or 3 > More > Test*) to determine how far it is to the remote area. The distance, stated in metres, will be shown in the lawnmower display when **STOP** has been pressed. See *How to measure the distance to a remote area on page 27*. The measured distance shown in the display can be saved directly to the selected remote area. The current value will be overridden by the new measured distance.



3.14.2.3 Area 1, 2 or 3 > How often?

How often the robotic lawnmower should be steered to the remote area is selected as a proportion of the total number of times it leaves the charging station. At all other times, the robotic lawnmower starts to mow at the charging station.

Select the percentage that corresponds to the size of the remote area relative to the total working area. If the remote area is for instance half of the total working area, 50% must be selected. A lower figure must be specified if the remote area is smaller. If more areas are used, take into account that the total figure cannot exceed 100%. Compare with the examples in *Yard layout examples on page 32*.



3.14.2.4 To set the lawn coverage

To set the lawn coverage follow below steps:

1. Use the left/right **arrow** keys to choose *Area 1, 2 or 3*.
2. Confirm by pressing the **OK** button.
3. Use the up/down **arrow** keys to change how far the robotic lawnmower should follow the guide wire.
4. Press the right **arrow** key and set how often this should be done.
5. Confirm by pressing the **OK** button.
6. Press the **Menu** button to go back to the overview menu of Lawn coverage.
7. Continue with the settings of next *Area*.

3.14.2.5 Area 1, 2 or 3 > Disable

Each area can be disabled and enabled without having to reenter the settings. Select *Disable* and press **OK**.

3.14.2.6 Area 1, 2 or 3 > More > Test

Testing selected settings can be seen as a natural part of the installation.

Using the *Test* function, the robotic lawnmower travels the farthest distance from the guide wire allowed by the corridor width.

Test: Area 1, 2 or 3

To test the selected settings:

1. Place the robotic lawnmower in the charging station.
2. Use the down and the right/left **arrow keys** to select the area to be tested from the *Lawn coverage overview* screen. Press **OK**.
3. Select *More* and press **OK**.
4. Select *Test* and press **OK**.
5. Press the **Start** button and close the hatch.
6. The robotic lawnmower will now leave the charging station and begin following the guide wire toward the remote area. Check that the robotic lawnmower can follow the guide wire all along the required distance.
7. The test is approved when the robotic lawnmower can follow the guide wire to the required starting point without any problem.

How to measure the distance to a remote area

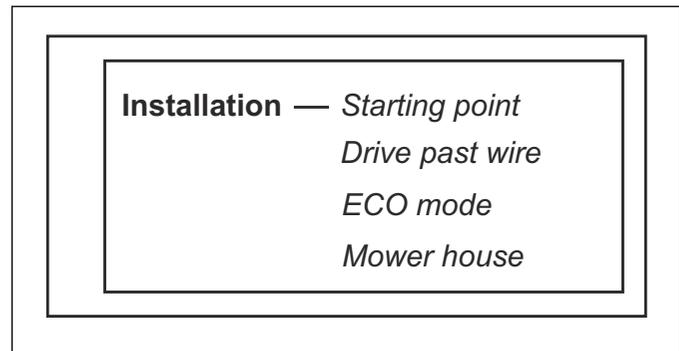
1. Park the robotic lawnmower in the charging station.
2. In the *Area 1, 2 or 3 > How far?* menu function, enter a distance which beyond any doubt exceeds the real figure. The maximum distance that can be entered is 500 metres.
3. Select *Area 1, 2 or 3 > More > Test* and press **OK**.
4. Press the **Start** button and close the hatch.
5. Press **STOP** at the required position. The distance is now shown in the display. This figure can now be saved in *Area 1, 2 or 3 > How far?*

Area 1, 2 or 3 > More > Reset

An individual area setting can be reset to the factory setting using this function. To reset an area setting, select *Area 1, 2 or 3 > More > Reset* using the left right **arrow keys** followed by **OK**.

3.14.3 Installation

For many working areas there is no need to change the factory settings but sometimes, depending on the lawn complexity, the mowing result can be improved by making manual settings.



3.14.3.1 Starting point

This functions allows you to control how far the robotic lawnmower drives from the charging station before it starts operating (mowing or lawn coverage). This is a useful function for instance if the charging station is placed under a veranda or in another limited space area.

Use the **number keys** to specify the required distance in centimetres. The factory setting is 60 cm and the maximum distance is 300 cm. See *First start-up on page 20*.

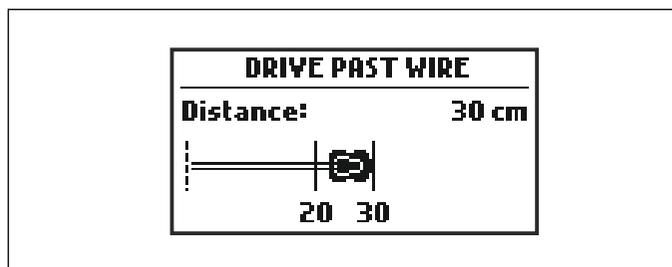
Note: Choosing a good starting point is important so that the guide calibration process can be optimized. See *Guide calibration on page 20*.

3.14.3.2 Drive past wire

The front of the robotic lawnmower always passes the boundary wire by a specific distance before the mower turns around. The default distance is 30 cm, but this can be changed if required. A figure between 20 and 30 can be selected.

Note that the distance given is only an approximate value. In reality, the actual distance the robotic mower passes the boundary wire can vary.

Use the up/down arrow keys to specify the number of centimetres that the robotic lawnmower should pass the boundary wire and press **OK**.



3.14.3.3 ECO mode

This function automatically turns off the signal in the boundary loop, the guide wires and the charging station when the robotic lawnmower is not mowing, i.e. when the lawnmower is charging or is not allowed to mow due to schedule settings.

ECO mode — Use ECO mode

ECO mode is suitable to use where there is other wireless equipment not compatible with the robotic lawnmower e.g. certain hearing loops or garage doors.

When *ECO mode* is activated, the indicator lamp in the charging station flashes green. *ECO mode* means that the robotic lawnmower can only be started in the charging station and not out in the working area.

In *ECO mode*, it is very important to always press the **STOP** button before removing the robotic lawnmower from the charging station. It is otherwise not possible to start the robotic lawnmower. If the lawnmower has been removed by mistake without first pressing the **STOP** button, the lawnmower must be placed back in the charging station and the **STOP** button pressed. Only then can the robotic lawnmower be started inside the working area.

Select *ECO mode* and press **OK** to activate *ECO mode*.

Note: Always press the **STOP** button before removing the robotic lawnmower from the charging station. In *ECO mode* the robotic lawnmower otherwise can not be started inside the working area.

3.14.3.4 Mower house

This menu is used to avoid collisions with the robotic lawnmower house. The function reduces wear on the robotic lawnmower body. However, it might leave uncut grass around the charging station.

Mower house — Avoid house collisions

3.14.4 General

In the General menu it is possible to set time and date, language and country. It is also possible to reset all user settings to factory default settings.

General — Time & date
Language
Country
Reset all user settings
About

3.14.4.1 Time & Date

This function allows you to set current time and date and required formats.

Time & Date — Set time
Set date
Time format
Date format

Set time

To set the time:

1. Enter the correct time by using the **up/down arrow keys**.
2. Press the **right arrow key** to be able to enter minutes.
3. Go back to *Time & Date* menu by pressing the **Menu** button.

Set date

To set the date:

1. Enter the correct date by using the **up/down arrow keys**.
2. Press the **right arrow key** to be able to enter month and day.
3. Go back to *Time & Date* menu by pressing the **Menu** button.

Time format

To set the time format:

1. Enter the required time format (24h or 12h) by using the **up/down arrow keys**.
2. Go back to *Time & Date* menu by pressing the **Menu** button.

Date format

To set the date format:

1. Enter the required date format by using the **up/down arrow keys**.
YYYY-MM-DD (year-month-day)
MM-DD-YYYY (month-day-year)
DD-MM-YYYY (day-month-year)
2. Go back to *Time & Date* menu by pressing the **Menu** button.

3.14.4.2 Language

To select language:

1. Use the **up/down arrow keys** to place the cursor at the required language.
2. Go back to *Time & Date* menu by pressing the **Menu** button.

3.14.4.3 Country

To select country:

1. Use the **up/down arrow keys** to place the cursor at the required country.
2. Go back to *Time & Date* menu by pressing the **Menu** button.

3.14.4.4 Reset all user settings

This function allows you to reset the robotic lawnmower to the factory default settings.

The following settings are however not altered:

- Security level

- PIN code
- Loop signal
- Date & Time
- Language
- Country

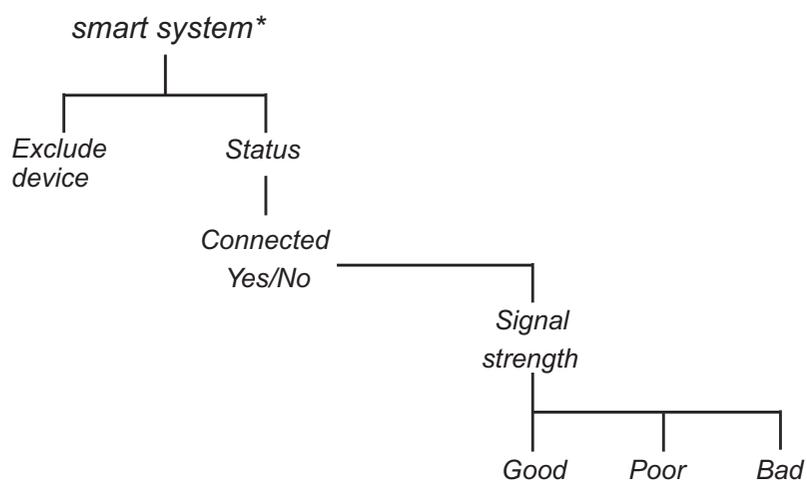
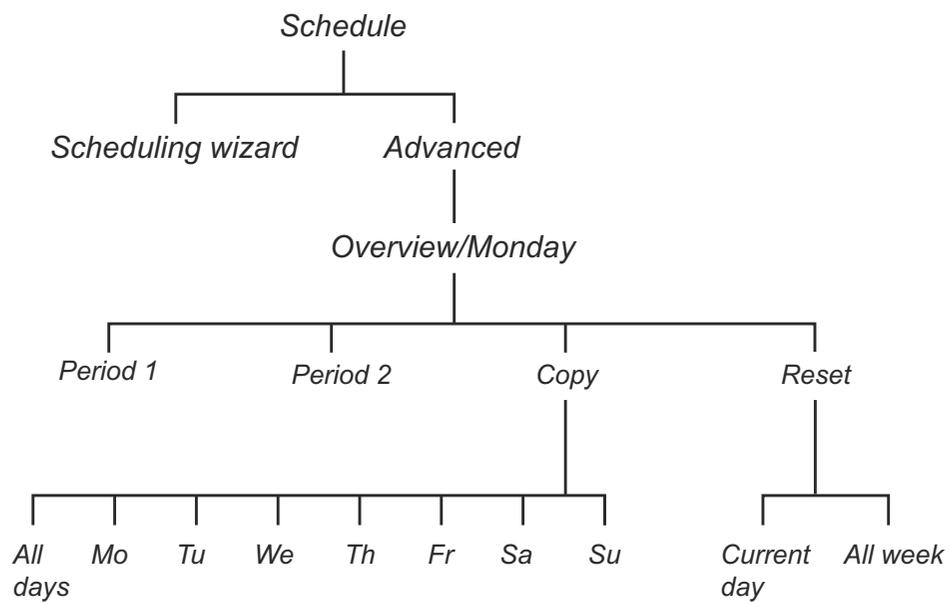
To Reset all user settings:

1. Select *Reset all user settings* in the menu and press **OK**.
2. Enter your pin code using the **up/down arrow keys** and press **OK**.
3. Use the **right arrow key** to place the cursor at *Yes*.
4. Confirm by pressing **OK**.

3.14.4.5 About

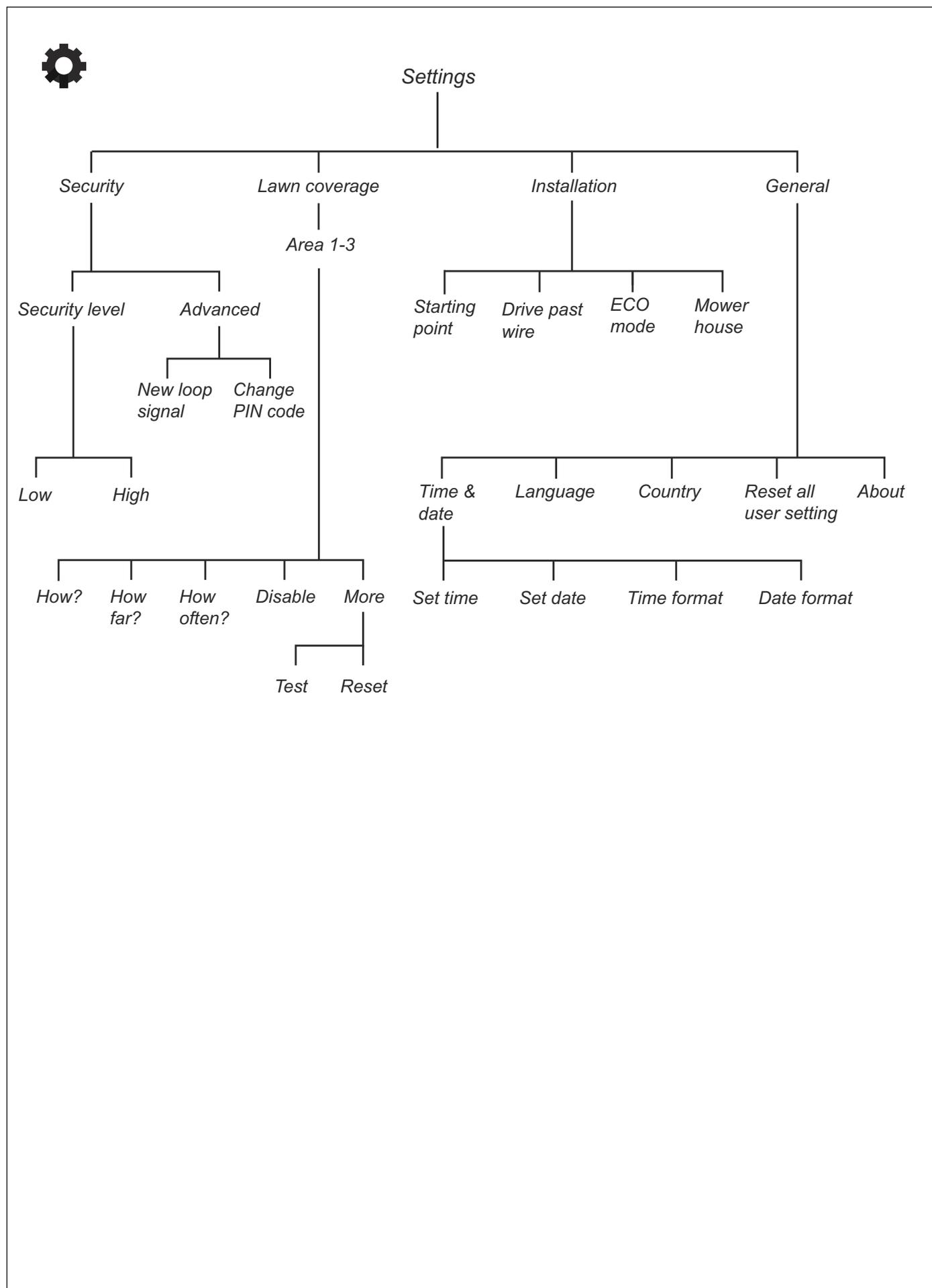
The *About* menu displays information about the robotic lawnmower's serial number, number of running hours and different software versions.

3.15 Menu structure overview



* smart SILENO city

3.16 Menu structure overview



3.17 Yard layout examples

The robotic mower's behaviour is controlled to a certain extent by what settings are made. Adapting the robotic lawnmower's settings according to the shape of the lawn makes it easier for the robotic lawnmower to frequently reach all parts and therefore achieve a perfect mowing result.

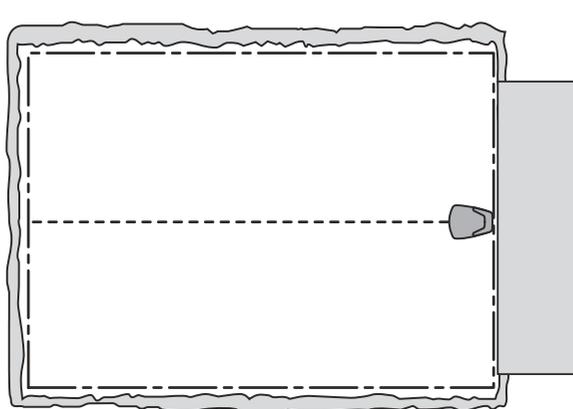
Different layouts require different settings. The following pages outline a number of layout examples with installation proposals and settings.

The recommended schedule settings in the following examples are applicable to SILENO city (for 500 m²) unless otherwise stated.

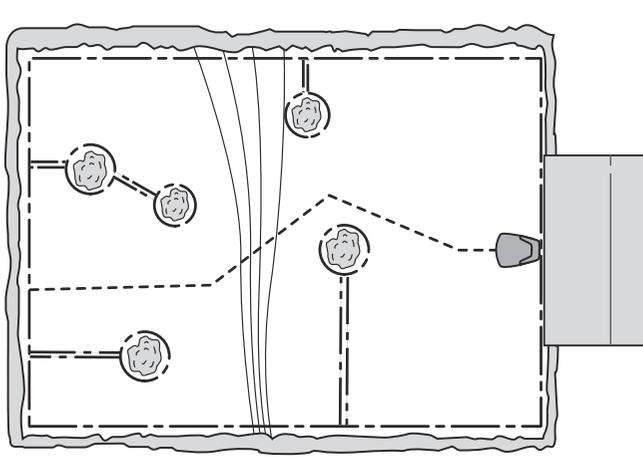
There is more installation help on www.gardena.com. Select country, then enter the supportpages for more information and videos.

Note: The default settings for the robotic lawnmower have been chosen to work in as many different gardens as possible. The settings only need to be adjusted when special installation conditions exist.

3.17.1 Open and level area

Area	150 m ²	
<i>Schedule</i>	SILENO city (for 500 m ²) 08:00 - 16:00, Monday, Wednesday, Friday	
<i>Lawn coverage</i>	Factory setting	
Remarks	The schedule should be used to prevent the grass looking trampled since the area is less than the maximum capacity of the robotic lawnmower.	

3.17.2 A number of islands and a 25% slope

Area	500 m ²	
<i>Schedule</i>	SILENO city (for 500 m ²) 08:00 - 19:00, Monday to Sunday	
<i>Lawn coverage</i>	Factory setting	
Remarks	Place the charging station in the lower part of the working area. Lay the guide wire at an angle over the steep slope. Make sure guide wire is laid according to recommendations in <i>Laying and connecting the guide wire on page 19</i>	

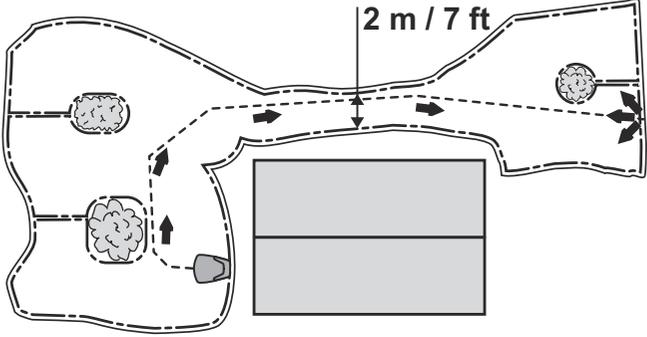
3.17.3 L-shaped garden with a couple of islands and the charging station installed in the narrow area

Area	500 m ²	
Schedule	SILENO city (for 500 m ²) 08:00 - 19:00, Monday to Sunday	
Lawn coverage	Area 1: <i>How?</i> Guide <i>How far?</i> X m <i>How often?</i> 60%	
Remarks	The <i>Lawn coverage</i> (<i>How often?</i>) for <i>Guide</i> must be specified as a value corresponding to the largest part of the working area as most of the working area can easily be reached by the robotic lawnmower following the guide wire out from the charging station. Make sure guide wire is laid according to recommendations in <i>Laying and connecting the guide wire on page 19</i> .	

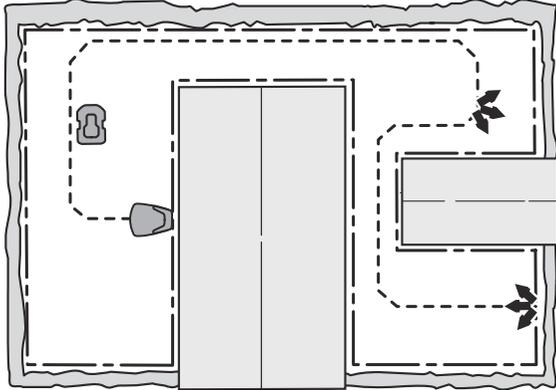
3.17.4 U-shaped garden linked with a narrow passage

Area	500 m ²	
Schedule	SILENO city (for 500 m ²) 08:00 - 19:00, Monday to Sunday	
Lawn coverage	Area 1: <i>How?</i> Guide <i>How far?</i> X m <i>How often?</i> 40%	
Remarks	The guide wire must be placed along the narrow passage to ensure that the robotic lawnmower can with ease locate the charging station from the left hand side of the working area. 40% is selected for <i>Lawn coverage, How often?</i> as the left hand area is nearly half of the total area. Make sure guide wire is laid according to recommendations in <i>Laying and connecting the guide wire on page 19</i> .	

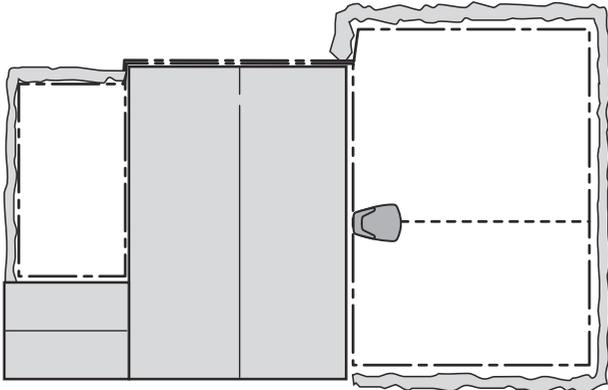
3.17.5 Unsymmetrical working area with a narrow passage and a number of islands

Area	500 m²	
<i>Schedule</i>	SILENO city (for 500 m ²) 08:00 - 19:00, Monday to Sunday	
<i>Lawn coverage</i>	Factory setting	
Remarks	The guide wire must be placed along the narrow passage to ensure that the robotic lawnmower can with ease locate the charging station from the right hand side of the working area. As the right hand area is only a small part of the working area, the <i>Lawn coverage</i> factory settings can be used. Make sure guide wire is laid according to recommendations in <i>Laying and connecting the guide wire</i> on page 19.	

3.17.6 3 areas linked with two narrow passages

Area	500 m²		
<i>Schedule:</i>	SILENO city (for 500 m ²) 08:00 - 19:00, Monday to Sunday		
<i>Lawn coverage</i>	Area 1: <i>How?</i> Guide <i>How far?</i> X m <i>How often?</i> 25 %	Area 2: <i>How?</i> Guide <i>How far?</i> X m <i>How often?</i> 25 %	
Remarks	As the working area contains three areas linked by two narrow passages, <i>Lawn coverage</i> must be used to create several areas to obtain an even mowing result across the entire working area. Make sure guide wire is laid according to recommendations in <i>Laying and connecting the guide wire</i> on page 19.		

3.17.7 A secondary area

Area	400 + 100 m²	
<i>Schedule</i>	SILENO city (for 500 m ²) 08:00 - 19:00, Monday to Saturday	
<i>Lawn coverage</i>	Factory setting	
Remarks	The secondary area is cut using the <i>Secondary area</i> mode on Sunday.	

4 Operation

4.1 The ON/OFF button



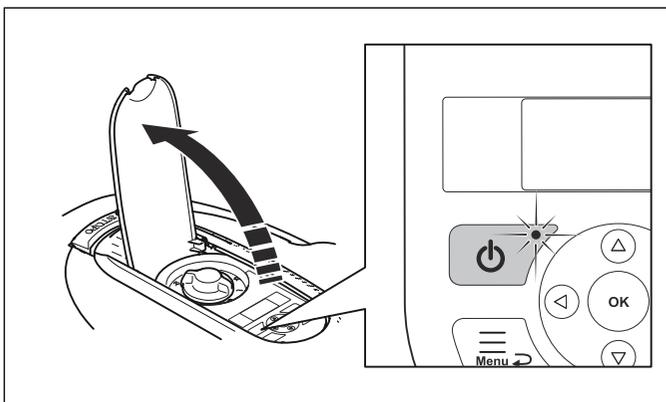
WARNING: Read the safety instructions carefully before you start your robotic lawnmower.



WARNING: Keep your hands and feet away from the rotating blades. Never put your hands or feet close to or under the machine when the motor is running.



WARNING: Never use the robotic lawnmower when persons, especially children, or pets, are in the cutting area.



- Press the **ON/OFF** button to turn the robotic lawnmower on. The robotic lawnmower is active when the lamp on the **ON/OFF** button is lit.
- Press the **ON/OFF** button to turn the robotic lawnmower off.

4.1.1 The indicator lamp

The indicator lamp on the **ON/OFF** button is an important status indicator:

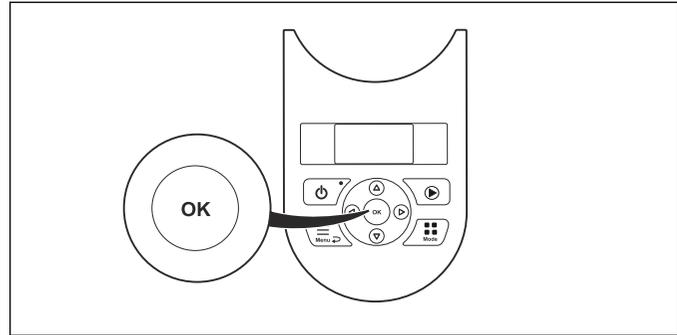
- The robotic lawnmower is active if the indicator lamp lights continuously.
- The robotic lawnmower is in standby if the indicator lamp flashes. This means that the operator must press the **ON/OFF** button to make the robotic lawnmower active again.
- The robotic lawnmower is disabled when the indicator lamp is not lit.



WARNING: It is only safe to carry out inspection or maintenance on the robotic lawnmower when the robotic lawnmower is disabled. The robotic lawnmower is disabled when the lamp on the **ON/OFF** button is not lit.

4.2 To start the robotic lawnmower

1. Open the hatch to the keypad.
2. Press the **ON/OFF** button. The display is lit up.
3. Enter the PIN code.
4. Press the **OK** button.



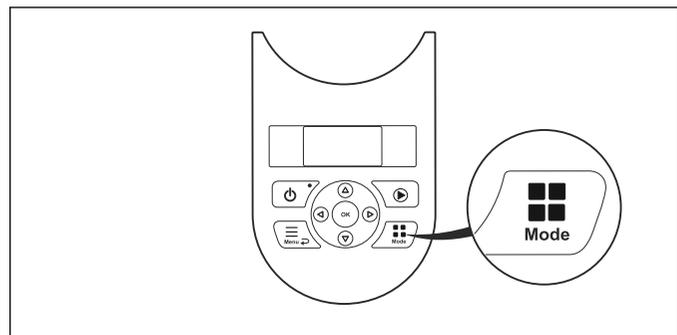
5. Select the desired operating mode and confirm with the **OK** button. See *Operating modes on page 35*.
6. Close the hatch.

Note: If the robotic lawnmower is parked in the charging station, the robotic lawnmower will only leave the charging station when the battery is fully charged and if the schedule allows the robotic lawnmower to operate.

4.3 Operating modes

When the **Mode** button is pressed the following operating modes can be selected:

- Main area
- Secondary area (2nd area)
- Park
- Park / Schedule
- Override schedule



4.3.1 Operating mode - Main area

Main area is the standard operating mode where the robotic lawnmower mows and charges automatically.

4.3.2 Operating mode - 2nd area

To mow secondary areas the operating mode *2nd area* must be chosen. Selecting *2nd area* means that the robotic lawnmower mows until the battery is empty.

If the robotic lawnmower is charged in the *2nd area* mode, it will fully charge, drive out about 50 cm and then stop. This indicates that the robotic lawnmower is charged and ready to start mowing. If the main working area is to be cut after charging, it is recommended to change the operating mode to *Main area* before placing the robotic lawnmower back in the charging station.

4.3.3 Operating mode - Park

Operating mode *Park* means that the robotic lawnmower remains in the charging station until a different operating mode is selected.

4.3.4 Operating mode - Park / Schedule

Operating mode Park / Schedule means that the robotic lawnmower remains in the charging station until the next schedule or standby permits operation. See *Schedule and Standby on page 36*.

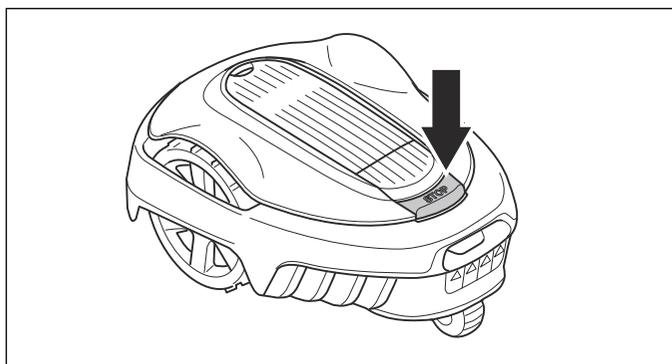
4.3.5 Operating mode - Override schedule

The schedule settings can be temporarily overridden by selecting *Override schedule*. It is possible to override the schedule for 3 h.

4.4 Stop

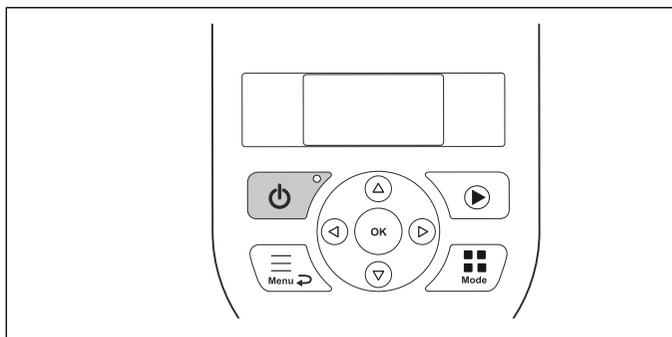
1. Press the **STOP** button.

The robotic lawnmower stops and the blade motor stops.



4.5 Switch off

1. Press the **STOP** button.
2. Open the hatch.
3. Press the **ON/OFF** button for 3 seconds.



4. The robotic lawnmower shuts down.
5. Check that the indicator lamp on the **ON/OFF** button is not lit.

4.6 Schedule and Standby

Use the Schedule function (see *Advanced on page 23*) to avoid a downtrodden lawn.

4.6.1 Standby

The robotic lawnmower has an inbuilt standby period according to the Standby time table. The standby period provides for instance a good opportunity to water or play games on the lawn.

Model	Standby time, minimum hours per day
500 m ²	13
400 m ²	15
350 m ²	17
250 m ²	19

4.6.2 To set the schedule

When setting the schedule, calculate that the robotic lawnmower mows about the amount of the number of square meters per hour and day listed in table Work capacity.

Model	Approximate work capacity, m ² per hour and day
500 m ²	45
400 m ²	43
350 m ²	49
250 m ²	49

If the working area is for example 250 m² in size, the robotic lawnmower must operate for 5-6 hours (depending on the robotic lawnmower's specified working area). Work capacity (m² per hour and day) is calculated by dividing the specified working area / active time per day. For example: 500 m² / 11h = 45 m².

The times are approximate and depend for instance on grass quality, blade sharpness and battery age.



WARNING: Use the schedule to avoid mowing when there are usually children, pets and anything else that could be damaged by the rotating blades on the lawn.

Use the wizard to set a suitable schedule depending on the size of the lawn. The wizard is taking the built-in standby time into account before suggesting the schedule. See *Scheduling wizard on page 22*.

4.6.3 Example 1

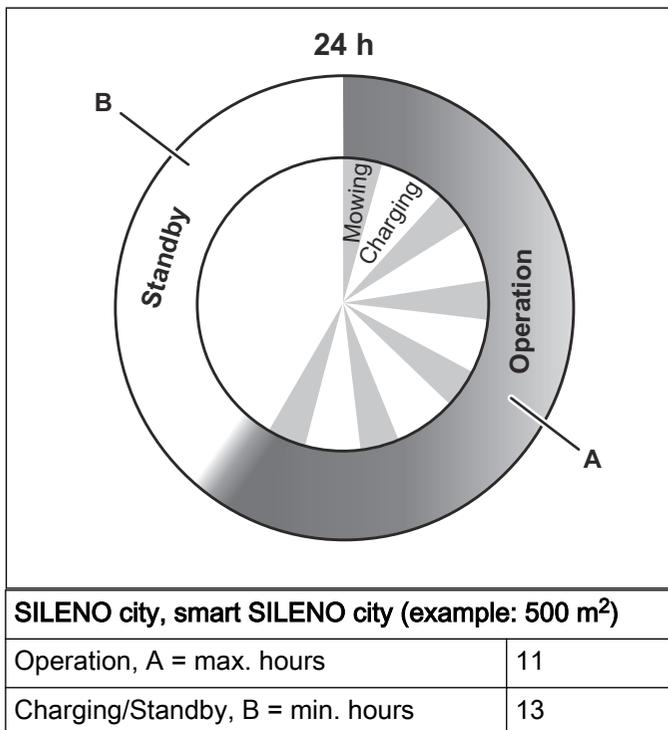
The times used in this example are applicable to SILENO city, smart SILENO city (500 m²), but the principle is the same for the other models.

Schedule setting, Period 1: 08:00 - 22:00.

Active period (A): 08:00 - 19:00.

The schedule settings ensure that the robotic lawnmower begins cutting the lawn at 08:00. However the mower is parked in standby mode in the charging station from 19:00 and rests until it starts cutting again at 08:00.

If the schedule setting is divided into 2 work periods, the standby period can be divided into a number of periods. The minimum standby period time must however be according to the Standby time table.



4.6.4 Example 2

The times used in this example are applicable to SILENO city, smart SILENO city (500 m²), but the principle is the same for the other models.

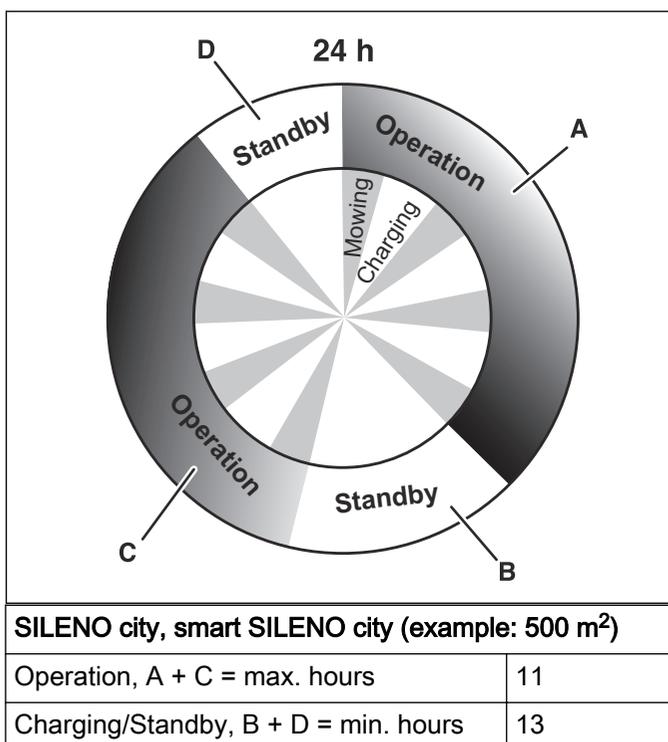
Schedule setting Period 1 (A): 08:00 - 17:00.

Schedule setting Period 2 (C): 20:00 - 23:00.

Active period (A): 08:00 - 17:00

Active period (C): 20:00 - 22:00.

The robotic lawnmower will operate between 08:00 and 17:00. It will begin again at 20:00 but stops running at 22:00 due to standby mode until it starts again at 08:00.



4.7 Charge a flat battery

When the GARDENA robotic lawnmower is new or has been stored for a long period, the battery will be flat and needs to be charged before starting.



WARNING: Only charge the robotic lawnmower using a charging station which is intended for it. Incorrect use may result in electric shock, overheating or leakage of corrosive liquid from the battery.

In the event of leakage of electrolyte flush with water and seek medical help if it comes in contact with the eyes etc.

1. Press the **ON/OFF** button to start the robotic lawnmower.
2. Place the robotic lawnmower in the charging station. Slide the robotic lawnmower in as far as possible to ensure proper contact between the robotic lawnmower and the charging station. See contact and charging strips in *Product overview on page 5*
3. The display shows a message that charging is in progress.

4.8 Adjust the cutting height

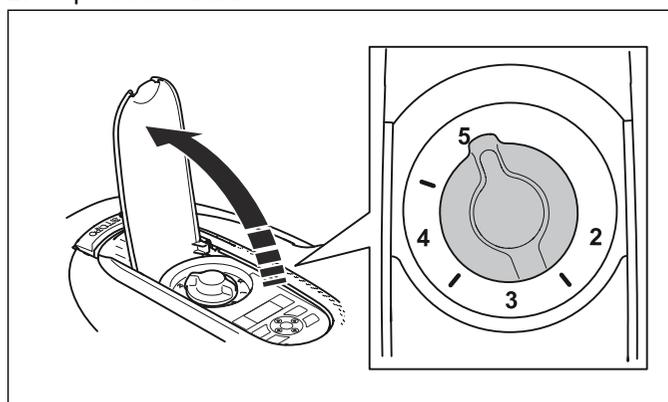
The cutting height can be varied from MIN (2 cm) to MAX (5 cm).



CAUTION: During the first weeks after a new installation, the cutting height must be set to MAX to avoid damaging the loop wire. After this, the cutting height can be lowered step by step every week until the desired cutting height has been reached.

4.8.1 To adjust the cutting height

1. Press the **STOP** button to stop the robotic lawnmower.
2. Open the hatch.



3. Turn the knob to the required position.
 - Turn clockwise to increase the cutting height.
 - Turn counter-clockwise to decrease the cutting height.
4. Close the hatch.

5 Maintenance

5.1 Introduction - maintenance

For better operating reliability and longer service life: check and clean the robotic lawnmower regularly and replace worn parts if necessary. All maintenance and servicing must be done according to GARDENA's instructions. See *Guarantee terms on page 53*.

When the robotic lawnmower is first used, the blade disc and blades should be inspected once a week. If the amount of wear during this period has been low, the inspection interval can be increased.

It is important that the blade disc rotates easily. The edges of the blades should not be damaged. The lifetime of the blades varies immensely and depends for instance on:

- Operating time and size of the working area.
- Type of grass and seasonal growth.
- Soil, sand and use of fertilizers.
- The presence of objects such as cones, windfalls, toys, tools, stones, roots and the like.

The normal life is 3 to 6 weeks when used under favorable conditions. See *To replace the blades on page 39* on how to replace the blades.

Note: Working with blunt blades gives a poorer mowing result. The grass is not cut cleanly and more energy is needed resulting in the robotic lawnmower not mowing such a large area.



WARNING: The robotic lawnmower must be turned off before any maintenance is done. The robotic lawnmower is disabled when the indicator lamp on the **ON/OFF** button is not lit.



WARNING: Wear protective gloves.

5.2 Clean the robotic lawnmower

It is important to keep the robotic lawnmower clean. A mower with large amounts of grass stuck to it will not cope as well with slopes. It is recommended to clean using a brush.

GARDENA offers a special cleaning and maintenance kit as an accessory. Please, contact GARDENA customer service.

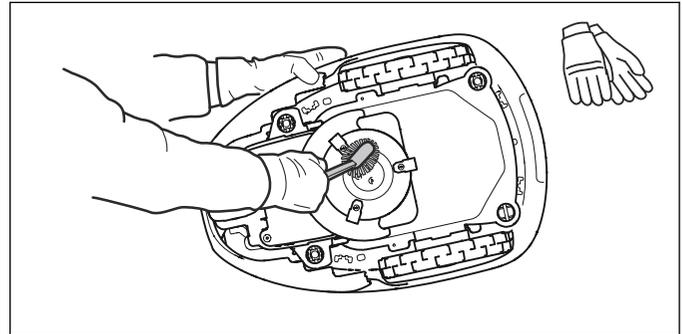


CAUTION: Never use a high-pressure washer to clean the robotic lawnmower. Never use solvents for cleaning.

5.2.1 Chassis and blade disc

1. Press the **ON/OFF** button for 3 seconds to turn off the robotic lawnmower.
2. Check that the indicator lamp on the **ON/OFF** button is not lit.

3. If the robotic lawnmower is very dirty, clean it by using a garden hose. Do not use a high-pressure washer.
4. Lift the robotic lawnmower onto its side.
5. Clean the blade disc and chassis using for example a dish brush. At the same time, check that the blade disc rotates freely in relation to the foot guard. Also, check that the blades are intact and can pivot freely. If long grass or other objects find their way in, these may impede the blade disc. Even a slight braking effect leads to a higher consumption of energy and at worst will prevent the robotic lawnmower from being able to mow the maximum working capacity.



5.2.2 Chassis

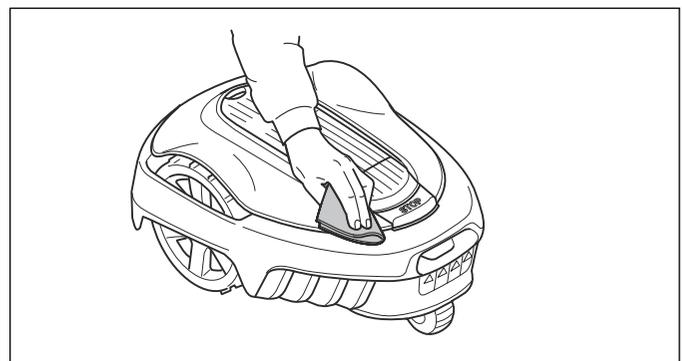
Clean the underside of the chassis. Brush or wipe with a damp cloth.

5.2.3 Wheels

Clean around the front wheels and rear wheel as well as the rear wheel bracket. Grass on the wheels can impact on how the lawnmower works in slopes.

5.2.4 Body

Use a damp, soft sponge or cloth to clean the body. If the body is very dirty it may be necessary to use a soap solution or washing-up liquid.



5.2.5 Charging station

Clean the charging station regularly from grass, leaves, twigs and other objects that may impede docking.

5.3 Replace the blades



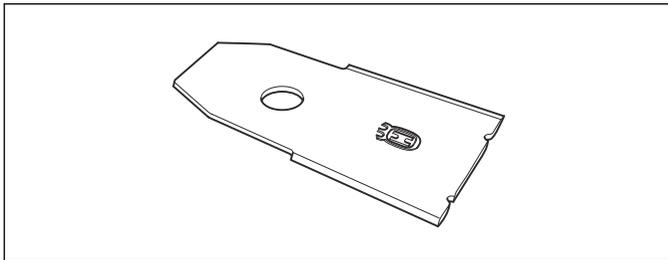
WARNING: Always use blades and screws of the right type. GARDENA can only guarantee safety when using original blades. Only replacing the blades and reusing the screw can

result in a screw wearing during mowing and shearing. The blades can then be propelled from under the body and cause serious injury.

Replace worn or damaged parts for safety reasons. Even if the blades are intact, they should be replaced on a regular basis for the best mowing result and low energy usage.

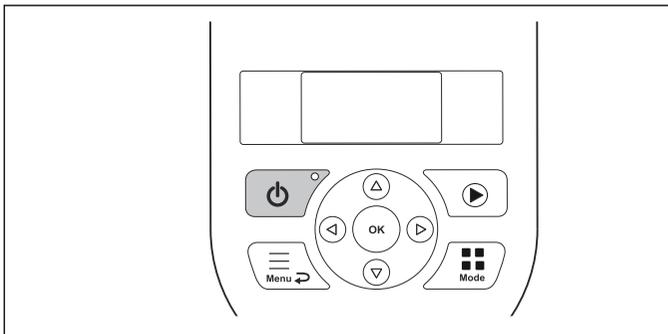
There are 3 blades on the robotic lawnmower, which are screwed into the blade disc. All 3 blades and screws must be replaced at the same time to obtain a balanced cutting system.

Use GARDENA original blades embossed with the crowned H-mark logotype, see *Guarantee terms on page 53*.

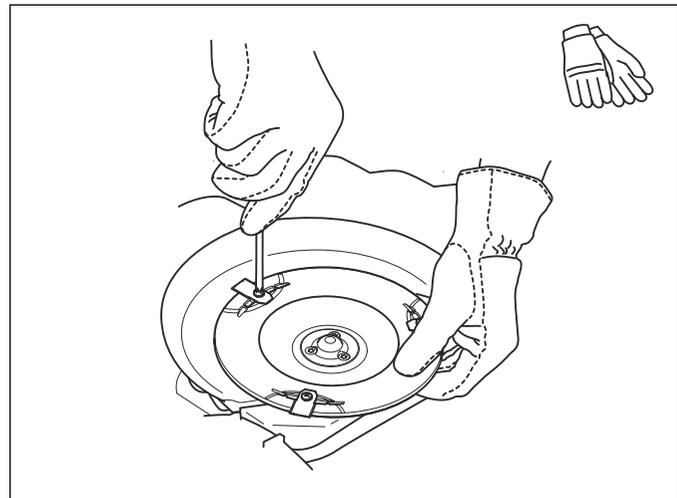


5.3.1 To replace the blades

1. Press the **STOP** button.
2. Open the hatch.
3. Press the **ON/OFF** button for 3 seconds to turn off the robotic lawnmower.



4. Check that the indicator lamp on the **ON/OFF** button is not lit.
5. Turn the robotic lawnmower upside down. Place the robotic lawnmower on a soft and clean surface to avoid scratching the body and the hatch.
6. Remove the 3 screws. Use a straight slot or cross-tip screwdriver.



7. Remove each blade and screw.
8. Fasten new blades and screws.
9. Check that the blades can pivot freely.

5.4 Software update

If service is done by GARDENA customer service then available software updates are downloaded to the robotic lawnmower by the service technician. However, owners of GARDENA robotic lawnmowers can update the software if this is initiated by GARDENA. Registered users will in that case be notified by email.

5.5 Battery

The battery is maintenance-free, but has a limited service life of 2 to 4 years.

Battery service life is dependent on the length of the season and how many hours a day the robotic lawnmower is used. A long season or many hours of use per day means that the battery must be replaced more regularly.



WARNING: Only charge the robotic lawnmower using a charging station which is intended for it. Incorrect use may result in electric shock, overheating or leakage of corrosive liquid from the battery. In the event of leakage of electrolyte flush with water and seek medical help if it comes in contact with the eyes etc.



CAUTION: The battery must be charged fully before winter storage. If the battery is not fully charged it can be damaged and in certain cases be rendered useless.

If the operating times for the robotic lawnmower are shorter than normal between charges, this indicates that the battery is getting old and eventually needs replacing. The battery is fine as long as the robotic lawnmower maintains a well-cut lawn.

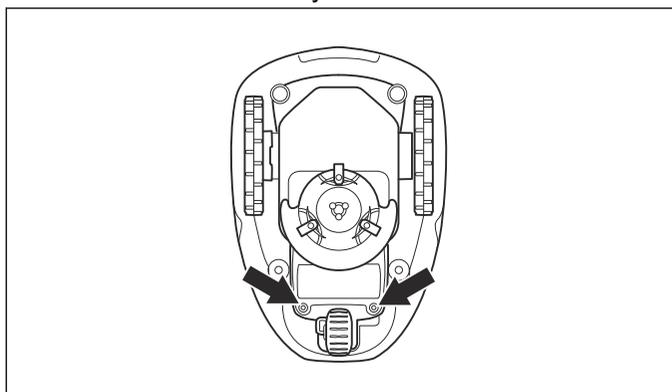
5.5.1 Replacing battery



WARNING: Use only original batteries recommended by the manufacturer. Product safety cannot be guaranteed with other

batteries. Do not use non-rechargeable batteries. The appliance must be disconnected from the supply mains when removing the battery.

1. Press the **ON/OFF** button for 3 seconds to turn off the robotic lawnmower.
2. Check that the indicator lamp on the **ON/OFF** button is not lit.
3. Turn the robotic lawnmower upside down. Place the robotic lawnmower on a soft and clean surface to avoid scratching the body and the display cover.
4. Clean around the battery cover.
5. Unscrew the screws to the battery cover (Torx 20) and remove the battery cover.

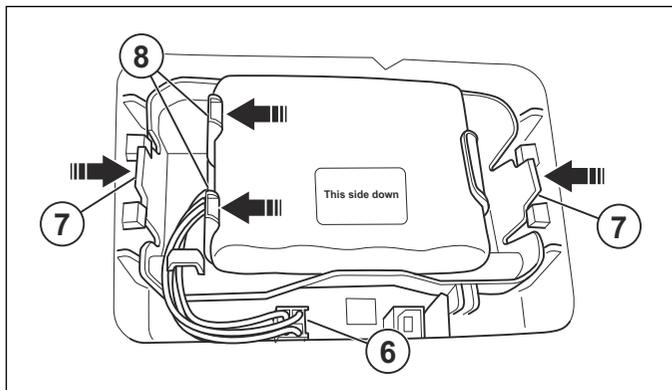


6. Release the latch of the connector and pull it upwards.



CAUTION: Do not pull the cables.

7. Release the latch of the battery holder and lift up the battery holder (including the battery) from the robotic lawnmower.



8. Release the latch of the battery and lift up the battery from the battery holder.
9. Place the new battery into the battery holder.

Note: The sticker "This side down" must be facing up when you place it into position. This means that "This side down" will be facing downwards when the robotic lawnmower is standing on its wheels.

10. Place the battery holder (including the battery) back into place in the robotic lawnmower.
11. Connect the cable

12. Fit the battery cover without clamping the cables. If the seal on the battery cover is visibly damaged, the entire battery cover must be replaced.
13. Carefully cross-tighten the four screws for the battery cover (Torx 20).

5.6 Winter service

Take your robotic lawnmower to GARDENA customer service for service prior to winter storage. Regular winter service will maintain the robotic lawnmower in good condition and create the best conditions for a new season without any disruptions.

Service usually includes the following:

- Thorough cleaning of the body, the chassis, the blade disc and all other moving parts.
- Testing of the mower's function and components.
- Checking and if required replacement of wear items such as blades and bearings.
- Testing the mower's battery capacity as well as a recommendation to replace battery if necessary.
- If necessary GARDENA customer service can also update the robotic lawnmower with new software, including new features where applicable.

6 Troubleshooting

6.1 Introduction - troubleshooting

In this chapter, a number of messages are listed which may be shown in the display if there is a malfunction. There is a proposal as to the cause and steps to take for each message. This chapter also presents some symptoms that can guide you if the robotic lawnmower does not work as expected. More suggestions for steps to take in the event of malfunction or symptoms can be found on www.gardena.com.

6.2 Fault messages

Below a number of fault messages are listed which may be shown in the display of the robotic lawnmower. Contact GARDENA customer service if the same message appears often.

Message	Cause	Action
<i>Wheel motor blocked, left</i>	Grass or other object has wrapped around the drive wheel.	Check the drive wheel and remove the grass or other object.
<i>Wheel motor blocked, right</i>	Grass or other object has wrapped around the drive wheel.	Check the drive wheel and remove the grass or other object.
<i>Cutting system blocked</i>	Grass or other object has wrapped around the blade disc.	Check the drive wheel and remove the grass or other object.
	The blade disc lies in a pool of water.	Move the robotic lawnmower and prevent the collection of water in the working area.
<i>No loop signal</i>	The power supply is not connected.	Check the wall socket connection and whether an earth-fault breaker has tripped or not. Check that the low voltage cable is connected to the charging station.
	The low voltage cable is damaged or not connected.	Check that the low voltage cable is not damaged. Check that it is also properly connected to the charging station and to the power supply.
	The boundary wire is not connected to the charging station.	Check that the boundary wire connectors are fitted properly to the charging station. Replace connectors if damaged. See <i>Connecting the boundary wire on page 18</i> .
	Boundary wire broken.	Find out where the break is. Replace the damaged section of the loop with a new loop wire and splice using an original coupler. See <i>Find breaks in the loop wire on page 47</i> .
	<i>ECO mode</i> is activated and the robotic lawnmower has attempted to start outside the charging station.	Place the robotic lawnmower in the charging station and press the STOP button. See <i>Settings on page 25</i> .
	The boundary wire is crossed on its way to and from an island.	Check that the boundary wire is laid according to instructions, e.g. in the right direction around the island. See <i>Installation on page 27</i> .
	The connection between the robotic lawnmower and the charging station has been broken.	Place the robotic lawnmower in the charging station and generate a new loop signal, see <i>New loop signal on page 25</i> .
	Disturbances from metal objects (fences, reinforcement steel) or buried cables close by.	Try moving the boundary wire.
<i>Trapped</i>	The robotic lawnmower has got caught in something.	Free the robotic lawnmower and rectify the reason for it becoming trapped.
	The robotic lawnmower is stuck behind a number of obstacles.	Check if there are any obstacles which make it hard for the robotic lawnmower to move on from this location.

Message	Cause	Action
<i>Outside working area</i>	The boundary wire connections to the charging station are crossed.	Check that the boundary wire is connected correctly.
	The boundary wire is too close to the edge of the working area.	Check that the boundary wire has been laid according to the instructions. See <i>Installation on page 27</i> .
	The working area slopes too much by the boundary loop.	
	The boundary wire is laid in the wrong direction around an island.	
	Disturbances from metal objects (fences, reinforcement steel) or buried cables close by.	Try moving the boundary wire.
	The robotic lawnmower finds it hard to distinguish the signal from another robotic lawnmower installation close by.	Place the robotic lawnmower in the charging station and generate a new loop signal, see <i>New loop signal on page 25</i> .
<i>Empty battery</i>	The robotic lawnmower cannot find the charging station.	Check that the charging station and the guide wire are installed in accordance with the instructions. See <i>Installation of the guide wire on page 18</i> .
	The guide wire is broken or not connected.	Find out where the break is and rectify it.
	The battery is spent.	Replace the battery. See <i>Battery on page 39</i> .
	The charging station's antenna is defective.	Check if the indicator lamp in the charging station flashes red. See <i>Indicator lamp in the charging station on page 45</i> .
<i>Wrong PIN code</i>	Wrong PIN code has been entered. Five attempts are permitted, and the keypad is then blocked for five minutes.	Enter the correct PIN code. Contact GARDENA customer service if you forget the PIN code.
<i>No drive</i>	The robotic lawnmower has got caught in something.	Free the robotic lawnmower and rectify the reason for the lack of drive. If it is due to wet grass, wait until the lawn has dried before using the robotic lawnmower.
	The working area includes a steep slope.	Maximum guaranteed slope is 40%. Steeper slopes should be isolated. See <i>Slopes on page 16</i> .
	The guide wire is not laid at an angle on a slope.	If the guide wire is laid on a slope, it must be laid at an angle across the slope. See <i>Installation of the guide wire on page 18</i> .
<i>Wheel motor overloaded, right</i>	The robotic lawnmower has got caught in something.	Free the robotic lawnmower and rectify the reason for the lack of drive. If it is due to wet grass, wait until the lawn has dried before using the robotic lawnmower.
<i>Wheel motor overloaded, left</i>		
<i>Charging station blocked</i>	The contact between the charging strips and contact strips may be poor and the robotic lawnmower has made a number of attempts to charge.	Put the robotic lawnmower in the charging station and check that the charging strips and contact strips make good contact.
	An object is obstructing the robotic lawnmower.	Remove the object.
	The charging station is tilted or bent.	Confirm that the charging station is placed on a fully flat and horizontal ground. The charging station must not be tilted or bent.

Message	Cause	Action
<i>Stuck in charging station</i>	There is an object in the way of the robotic lawnmower preventing it from leaving the charging station.	Remove the object.
<i>Upside down</i>	The robotic lawnmower is leaning too much or has turned over.	Turn the robotic lawnmower the right way up.
<i>Needs manual charging</i>	The robotic lawnmower is set to the <i>Secondary area</i> operating mode.	Place the robotic lawnmower in the charging station. This behaviour is normal and no action is required.
<i>Next start hh:mm</i>	The schedule setting prevents the robotic lawnmower from operating.	Change the schedule settings. See <i>Advanced on page 23</i> .
	The rest period is in progress. The robotic lawnmower has an inbuilt standby period according to the Standby time table.	This behaviour is normal and no action is required. See <i>Schedule and Standby on page 36</i> .
	The clock on the robotic lawnmower is not correct.	Set the time. See <i>To set the schedule on page 36</i> .
<i>Today's mowing completed</i>	The rest period is in progress. The robotic lawnmower has an inbuilt standby period according to the Standby time table.	This behaviour is normal and no action is required. See <i>Schedule and Standby on page 36</i> .
<i>Lifted</i>	The lift sensor has been activated as the mower has become trapped.	Free the mower
<i>Collision sensor problem, front/rear</i>	Mower body can not move freely around its chassis.	Check that the mower body can move freely around its chassis. If the problem remains, the message requires action by authorized service technician.
<i>Wheel drive problem, right/left</i>	Grass or other object is wrapped around the drive wheel.	Clean the wheels and around the wheels.
<i>Safety function faulty</i>	Temporary electronic or software related issue in the mower.	Restart the mower. If the problem remains, the message requires action by authorized service technician.
<i>Electronic problem</i>		
<i>Loop sensor problem, front/rear</i>		
<i>Charging system problem</i>		
<i>Tilt sensor problem</i>		
<i>Temporary problem</i>		
<i>Temporary battery problem</i>	Temporary battery or software related issue in the mower.	Restart the mower. Disconnect and reconnect the battery. If the problem remains, the message requires action by authorized service technician.
<i>Battery problem</i>		
<i>Charging current too high</i>	Wrong or faulty power supply unit.	Restart the mower. If the problem remains, the message requires action by authorized service technician.
<i>Connectivity problem</i>	Potential problem on the connectivity circuit board in the mower.	Restart the mower. If the problem remains, the message requires action by authorized service technician.
<i>Connectivity settings restored</i>	The connectivity settings was restored due to a fault.	Please check and change the settings if needed.
<i>Poor signal quality</i>	The connectivity circuit board in the mower is assembled upside down, or the mower itself is tilted or upside down.	Verify the mower is not upside down or tilted. If not, the message requires action by authorized service technician.

6.3 Information messages

Below a number of information messages are listed which may be shown in the display of the robotic lawnmower. Contact GARDENA customer service if the same message appears often.

Message	Cause	Action
<i>Low battery</i>	The robotic lawnmower cannot find the charging station.	Check that the charging station and the guide wire are installed in accordance with the instructions. See <i>Installation of the guide wire on page 18</i> .
	The guide wire is broken or not connected.	Find out where the break is and rectify it.
	The battery is spent.	Replace the battery. See <i>Battery on page 39</i> .
	The charging station's antenna is defective.	Check if the indicator lamp in the charging station flashes red. See <i>Indicator lamp in the charging station on page 45</i> .
<i>Settings restored</i>	Confirmation that a <i>Reset all user settings</i> has been carried out.	This is normal. No action required.
<i>Guide not found</i>	The guide wire is not connected to the charging station.	Check that the guide wire's connector is tightly connected to the charging station. See <i>Installation of the guide wire on page 18</i> .
	Break in the guide wire.	Find out where the break is. Replace the damaged section of the guide wire with a new loop wire and splice using an original coupler.
	The guide wire is not connected to the boundary loop.	Check that the guide wire is connected correctly to the boundary loop. See <i>Laying and connecting the guide wire on page 19</i> .
<i>Guide calibration failed</i>	The robotic lawnmower has failed to calibrate the guide wire.	Check that the guide wires are installed according to the instructions, See <i>Installation of the guide wire on page 18</i> . Also, check that the minimum distance to the left of the guide wire is met. See <i>First start-up on page 20</i> .
<i>Guide calibration accomplished</i>	The robotic lawnmower has succeeded to calibrate the guide wire.	No action required.

6.4 Indicator lamp in the charging station

For a fully functional installation, the indicator lamp in the charging station must emit a solid or flashing green light. If something else appears, follow the troubleshooting guide below.

There is more help on www.gardena.com. If you still need help, please contact GARDENA customer service.

Light	Cause	Action
<i>Solid green light</i>	Good signals	No action required
<i>Green flashing light</i>	The signals are good and <i>ECO mode</i> is activated.	No action required. For more information on <i>ECO mode</i> , see <i>Settings on page 25</i> .
<i>Blue flashing light</i>	The boundary loop is not connected to the charging station.	Check that the boundary wire connectors are fitted properly to the charging station. See <i>Connecting the boundary wire on page 18</i> .
	Break in the boundary loop.	Find out where the break is. Replace the damaged section of the loop with a new loop wire and splice using an original coupler.
<i>Yellow flashing light</i>	The guide wire is not connected to the charging station.	Check that the guide wire connector is properly connected to the charging station. See <i>Laying and connecting the guide wire on page 19</i>
	Break in the guide wire.	Find out where the break is. Replace the damaged section of the guide wire with a new loop wire and splice using an original coupler.
<i>Red flashing light</i>	Interruption in the charging station's antenna.	Contact GARDENA customer service.
<i>Solid red light</i>	Fault in the circuit board or incorrect power supply in the charging station. The fault should be rectified by an authorized service technician.	Contact GARDENA customer service.

6.5 Symptoms

If your robotic lawnmower does not work as expected, follow the symptoms guide below.

There is a FAQ (Frequently Asked Questions) on www.gardena.com which provides more detailed answers to a number of standard questions. Contact GARDENA customer service if you still cannot find the reason for the fault.

Symptoms	Cause	Action
The robotic lawnmower has difficulty docking.	The boundary wire is not laid in a long straight line that is far enough out from the charging station.	Check that the charging station has been installed according to the instructions in <i>Installing and connecting the charging station on page 13</i>
	The guide wire is not inserted in the slot under the charging station.	It is absolutely critical for operation that the guide wire is perfectly straight and is in the correct position under the charging station. Therefore make sure that the guide wire is always in its slot in the charging station. See <i>Laying and connecting the guide wire on page 19</i> .
	The charging station is on a slope.	Place the charging station on a surface that is entirely level. See <i>Best charging station location on page 11</i> .
The robotic lawnmower runs at the wrong time	The robotic lawnmower clock needs to be set.	Set the clock. See <i>Time & Date on page 28</i> .
	The start and stop times for mowing are incorrect.	Reset the start time and stop time settings for mowing. See <i>Advanced on page 23</i> .
The robotic lawnmower vibrates.	Damaged blades lead to imbalance in the cutting system.	Inspect the blades and screws and replace them if necessary. See <i>To replace the blades on page 39</i> .
	Too many blades in the same position lead to imbalance in the cutting system.	Check that only one blade is fitted at each screw.
	Different versions (thickness) of GARDENA blades are used.	Check if the blades are of different versions.
The robotic lawnmower runs, but the blade disc does not rotate.	The robotic lawnmower searches for the charging station.	No action. The blade disc does not rotate when the robotic lawnmower is searching for the charging station.
The robotic lawnmower mows for shorter periods than usual between charges.	Grass or other foreign object blocks the blade disc.	Remove and clean the blade disc. See <i>Clean the robotic lawnmower on page 38</i> .
	The battery is spent.	Replace the battery. See <i>Battery on page 39</i> .
Both the mowing and charging times are shorter than usual.	The battery is spent.	Replace the battery. See <i>Battery on page 39</i> .
The robotic lawnmower is parked for hours in the charging station.	The robotic lawnmower has an inbuilt standby period according to the Standby time table. See <i>Standby on page 36</i> .	No action.
	The STOP button has been activated.	Open the hatch, enter the PIN code and confirm with the OK button. Press the Start button and then close the hatch.

Symptoms	Cause	Action
Uneven mowing results.	The robotic lawnmower works too few hours per day.	Increase the mowing time. See <i>Advanced on page 23</i> .
	The shape of the working area requires the use of <i>Area 1-3</i> for the robotic lawnmower to find its way to all remote areas.	Use <i>Area 1-3</i> to steer the robotic lawnmower to a remote area. See <i>Lawn coverage on page 26</i> .
	The <i>How often?</i> setting is incorrect in relation to the layout of the working area.	Check that the correct <i>How often?</i> value is selected.
	Working area too large.	Try limiting the working area or extending the working time. See <i>Advanced on page 23</i> .
	Dull blades.	Replace all the blades. See <i>To replace the blades on page 39</i> .
	Long grass in relation to the set cutting height.	Increase the cutting height and then successively lower it.
	Accumulation of grass by the blade disc or around the motor shaft.	Check that the blade disc rotates freely and easily. If not, screw off the blade disc and remove grass and foreign objects. See <i>Clean the robotic lawnmower on page 38</i> .

6.6 Find breaks in the loop wire

Breaks in the loop wire are usually the result of unintentional physical damage to the wire such as when gardening with a shovel. In countries with ground frost, also sharp stones that move in the ground can damage the wire. Breaks can also occur due to the wire being stretched excessively during installation.

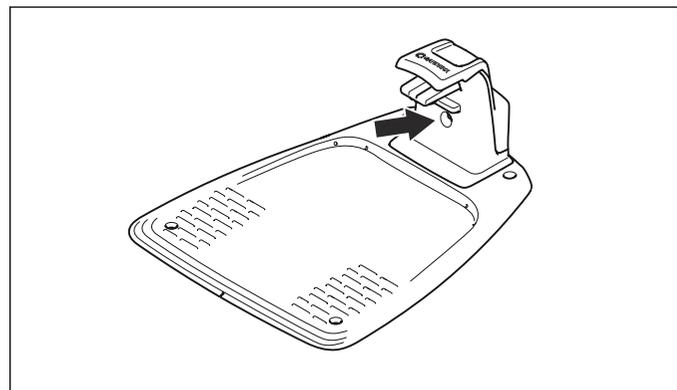
Mowing the grass too low right after the installation can damage wire insulation. Damage to the insulation may not cause disruptions until several weeks or months later. To avoid this, always select the maximum cutting height the first weeks after installation and then lower the height one step at a time every second week until the desired cutting height has been reached.

A defective splicing of the loop wire can also lead to disruptions several weeks after the splice was done. A faulty splice can, for example, be the result of the original coupler not being pressed together hard enough with a pair of pliers, or that a coupler of lower quality than the original coupler has been used. Please first check all known splices before further troubleshooting is done.

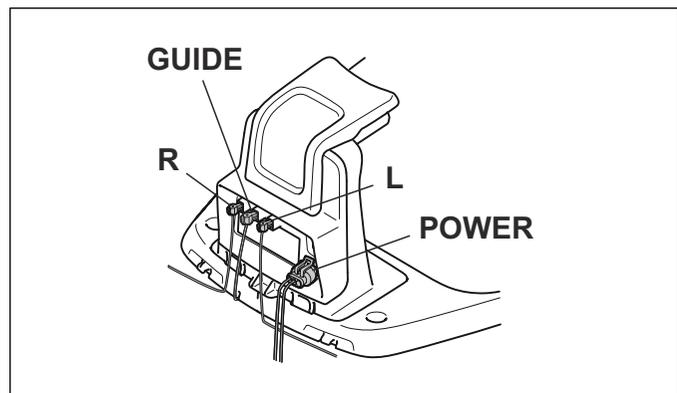
A wire break can be located by gradually halving the distance of the loop where the break may have occurred until there is only a very short section of the wire left.

The following method does not work if *ECO mode* is activated. Make sure first that *ECO mode* is turned off. See *ECO mode on page 28*.

1. Check that the indicator lamp in the charging station flashes blue, which indicates a break in the boundary loop. See *Indicator lamp in the charging station on page 45*.



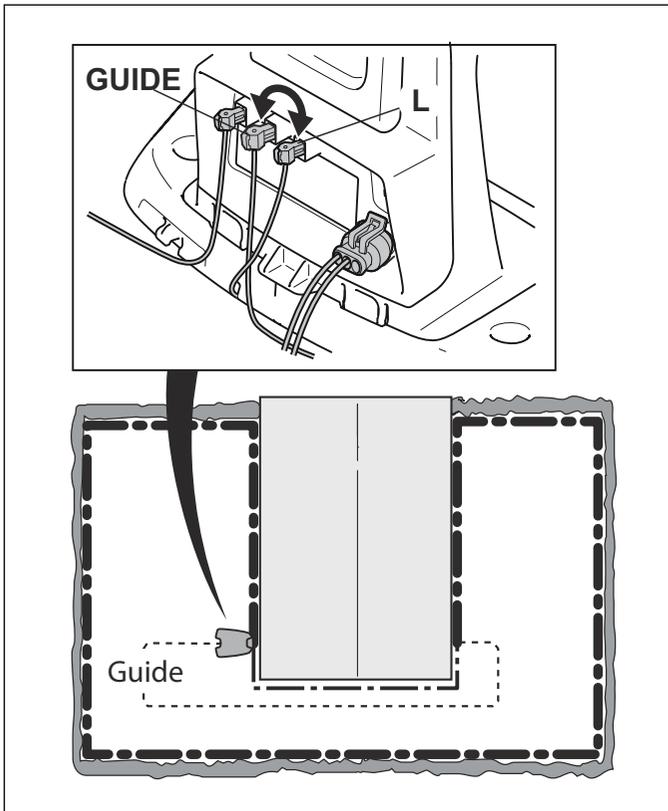
2. Check that the boundary wire connections to the charging station are properly connected and not damaged. Check that the indicator lamp in the charging station is still flashing blue.



3. Switch the connections between the guide wire and the boundary wire in the charging station.

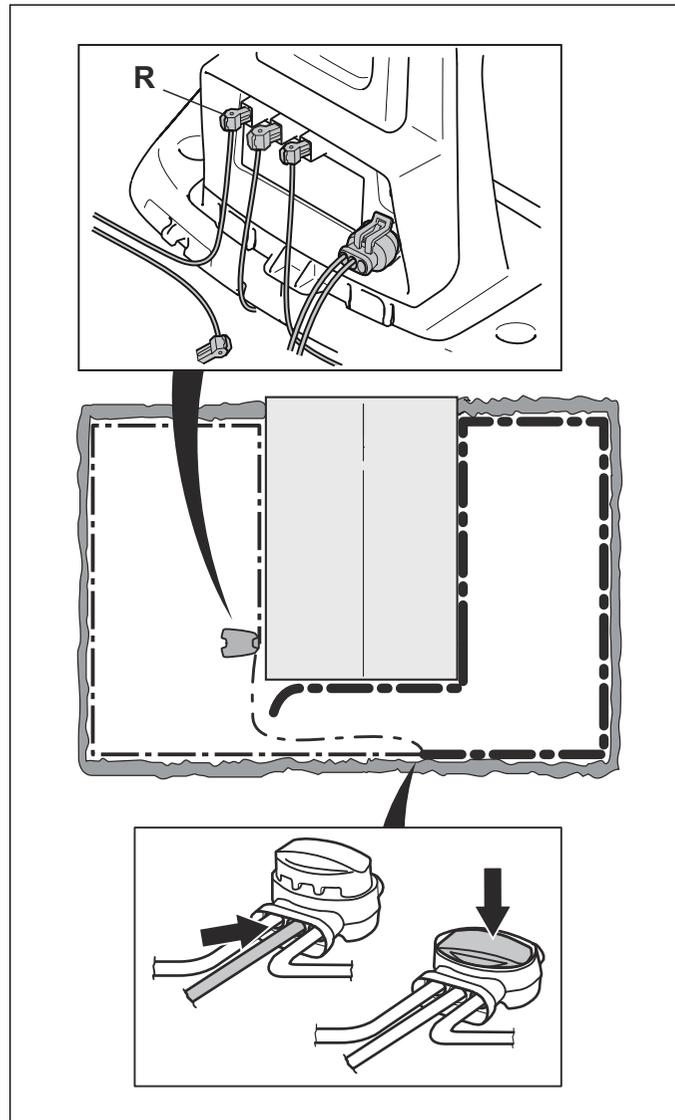
Start by switching connection L and GUIDE.

If the indicator lamp is lit with a solid green light, then the break is somewhere on the boundary wire between L and the point where the guide wire is connected to the boundary wire (thick black line in the illustration).

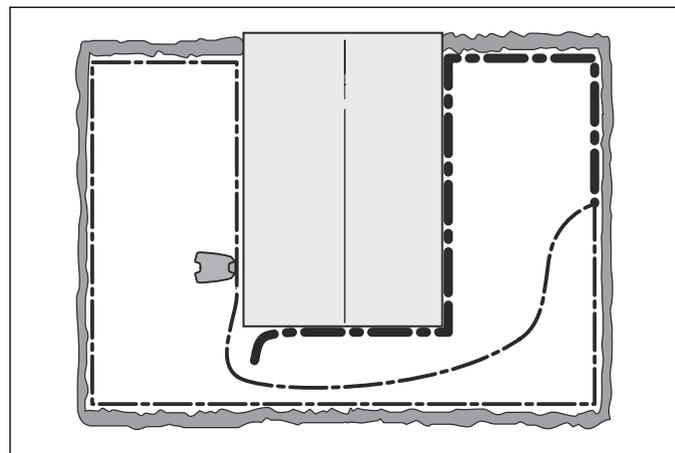


To rectify the fault you will need boundary wire, connector(s) and coupler(s):

- a) If the suspected boundary wire is short then it is easiest to exchange all of the boundary wire between L and the point where the guide wire is connected to the boundary wire (thick black line).
- b) If the suspected boundary wire is long (thick black line) then do as follows: Put L and GUIDE back to their original positions. Then disconnect R. Connect a new loop wire to R. Connect the other end of this new loop wire at the middle of the suspected wire section.

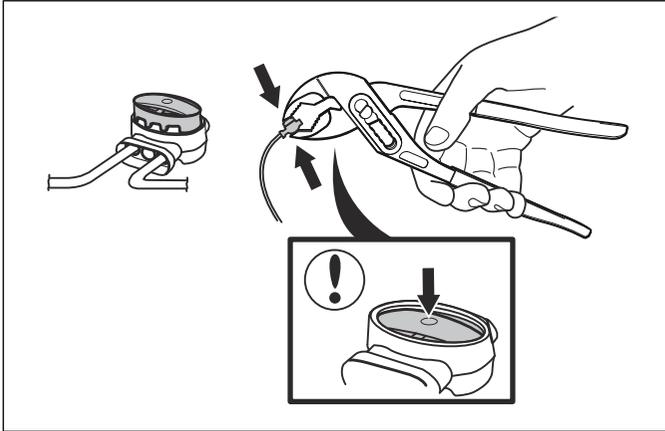


If the indicator lamp now is green, then the break is somewhere in the wire between the disconnected end to the point where the new wire is connected (thick black line below). In that case, move the connection for the new wire closer to the disconnected end (roughly at the middle of the suspected wire section) and check again if the indicator lamp is green.



Continue until only a very short section of the wire remains which is the difference between a solid green light and a flashing blue light. Then follow instruction in step 5 below.

4. If indicator lamp still flashes blue in step 3 above: Put L and GUIDE back in their original positions. Then switch R and GUIDE. If indicator lamp now is lit with a solid green light then disconnect L and connect a new boundary wire to L. Connect the other end of this new wire at the middle of the suspected wire section. Follow the same approach as in 3a) and 3b) above.
5. When the break is found, the damaged section must be replaced with a new wire. Always use original couplers.



7 Transportation, storage and disposal

7.1 Transportation

The contained lithium-ion-batteries are subject to the Dangerous Goods Legislation requirements. For commercial transports e.g. by third parties or forwarding agents, special requirement on packaging and labeling must be observed. Consult an expert for hazardous material for preparation of the item being shipped. Please also observe possibly more detailed national regulations.

Tape off open contacts and pack up the battery in such a manner that it cannot move around in the packaging. Always secure the product when transporting it.

7.2 Winter storage

7.2.1 The robotic lawnmower

Clean the robotic lawnmower carefully before putting it away for the winter. See *Clean the robotic lawnmower on page 38*.

To guarantee battery functionality and service life, it is important to charge the robotic lawnmower before storing it away for the winter. Place the robotic lawnmower in the charging station with the hatch open until the battery icon in the display shows that the battery is fully charged. Then turn off the robotic lawnmower by pressing the **ON/OFF** button. Check that the indicator lamp on the **ON/OFF** button is not lit.

Check the condition of wear items such as blades and bearings in the rear wheel. Rectify if necessary to make sure the robotic lawnmower is in good condition prior to next season.

Store the robotic lawnmower standing on all wheels and place it in a dry, frost-free environment, preferably in the mower's original packaging. You can also hang the robotic lawnmower on a GARDENA original wall hanger. Contact GARDENA customer service for more information about available wall hangers.



CAUTION: The battery must be charged fully before winter storage. If the battery is not fully charged it can be damaged and in certain cases be rendered useless.

7.2.2 The charging station

It is recommended to store the charging station and power supply indoors. The boundary wire and the guide wire can be left in the ground.

1. Disconnect the charging station power supply.
2. Release the connector lock of the power supply, and pull the connector out.
3. Disconnect the boundary and guide wire connectors from the charging station.

The ends of the wires should be protected from damp by putting them in a container with grease for instance. GARDENA offers a special box to protect the wire ends

during the winter. Please, contact GARDENA customer service.



CAUTION: If the charging station is left outdoors during the winter, the charging station must be connected to the mains, the boundary wire and the guide wires the entire winter.

7.3 After winter storage

1. Check if cleaning is needed, particularly the charging strips on both the robotic lawnmower and the charging station.
2. If the charging strips appear to be burnt or coated, clean them using a fine grade emery cloth.
3. Check also that the robotic lawnmower's time and date are correct.

7.4 Environmental information



The symbol on the GARDENA robotic lawnmower indicates that this product cannot be treated as domestic waste. It should instead be left at a suitable recycling centre to recycle its electronic components and batteries. The battery must be removed from the product before it is scrapped.

By ensuring that this product is taken care of correctly, you can help to counteract the potential negative impact on the environment and people that can otherwise result through incorrect waste management of this product.

For more detailed information about recycling this product, contact your municipality, your domestic waste service or the shop from where you purchased the product.

7.5 Removal of battery for recycling

For removal the battery from the robotic lawnmower see *Replacing battery on page 39*.

8 Technical data

8.1 Technical data

Data	SILENO city	smart SILENO city
Dimensions		
Length, cm	55	55
Width, cm	38	38
Height, cm	23	23
Weight, kg	7.3	7.3

Electrical system	SILENO city	smart SILENO city
Battery, Lithium-Ion 18 V/2.1 Ah Art.No	584 85 28-01, 584 85 28-02	
Power supply, V/28 V DC	100-240	100-240
Low voltage cable length, m	5	5
Mean energy consumption at maximum use	3.9 kWh/month in a 500 m ² working area	3.9 kWh/month in a 500 m ² working area
Charge current, A DC	1.3	1.3
Average mowing time, min	60	60
Average charging time, min	60	60

Boundary wire antenna	SILENO city	smart SILENO city
Operating Frequency Band, Hz	300-80000	300-80000
Maximum Radio-frequency power, mW @60m ¹	<25	<25

Noise emissions measured in the environment as sound power ²	SILENO city	smart SILENO city
Measured sound power noise level, dB (A)	56	56
Noise emissions uncertainties K _{WA} , dB (A)	2	2
Guaranteed sound power noise level, dB (A)	58	58
Sound pressure noise level at the operator's ear, dB (A) ³	45	45

The noise emission declarations conforms to EN 50636-2-107:2015

Mowing	SILENO city	smart SILENO city
Cutting system	3 pivoted cutting blades	
Blade motor speed, rpm	2500	2500
Power consumption during cutting, W +/- 20 %	20	20
Cutting height, cm	2-5	2-5
Cutting width, cm	16	16
Narrowest possible passage, cm	60	60
Maximum slope for cutting area, %	25	25
Maximum slope for boundary wire, %	10	10

¹ Maximum active output power to antennas in the frequency band in which the radio equipment operates.

² Noise emissions in the environment measured as sound power (L_{WA}) in conformity with EC directive 2000/14/EC. The guaranteed sound power level includes variation in production as well as variation from the test code with 1-3 dB(A).

³ Sound pressure noise uncertainties K_{pA}, 2-4 dB (A)

Mowing	SILENO city	smart SILENO city
Maximum length boundary wire, m	300	300
Maximum length guide wire, m	150	150
Working capacity, m ² +/- 20% (depending on product specification)	- 700	- 700
IP-classification	SILENO city	smart SILENO city
Robotic lawnmower	IPX5	IPX5
Charging station	IPX5	IPX5
Power supply	IPX4	IPX4
Internal SRD (short range device)	SILENO city	smart SILENO city
Operating frequency band, MHz	-	863-870
Maximum transmitted power, dBm	-	14
Free field radio range, approx. m	-	100
Bluetooth®	SILENO city	smart SILENO city
Operating frequency band, MHz	2400 - 2484	2400 - 2484
Maximum transmitted power, dBm	8	8

Husqvarna AB does not guarantee full compatibility between the robotic lawnmower and other types of wireless systems such as remote controls, radio transmitters, hearing loops, underground electric animal fencing or similar.

9 Warranty

9.1 Guarantee terms

GARDENA guarantees this product's functionality for a period of two years (from date of purchase). The guarantee covers serious faults relating to materials or manufacturing faults. Within the guarantee period, we will replace the product or repair it at no charge if the following terms are met:

- The robotic lawnmower and the charging station may only be used in compliance with the instructions in this Operator's Manual. This manufacturer's guarantee does not have an effect on the user's existing warranty claims against the dealer/seller.
- End-users or non-authorized third parties must not attempt to repair the product.

Examples of faults which are not included in the guarantee:

- Damage caused by water seepage from using a high-pressure washer, or from being submerged under water, for example when heavy rain forms pools of water.
- Damage caused by lightning.
- Damage caused by improper battery storage or battery handling.
- Damage caused by using a battery that is not a GARDENA original battery.
- Damage caused by not using GARDENA original spare parts and accessories, such as blades and installation material.
- Damage to the loop wire.
- Damage caused by non-authorized changing or tampering with the product or its power supply.

The blades and wheels are seen as disposable and are not covered by the guarantee.

If an error occurs with your GARDENA robotic lawnmower, please contact GARDENA customer service for further instructions. Please have the receipt and the robotic lawnmower's serial number at hand when contacting GARDENA customer service.

10 EC Declaration of Conformity

10.1 EC Declaration of Conformity

Husqvarna AB, SE-561 82 Huskvarna, Sweden, tel: +46-36-146500, declares that the Robotic lawnmowers **GARDENA SILENO city** and **GARDENA smart SILENO city** with serial numbers dating 2017 week 48 and onwards (the year and week is clearly stated on the rating plate, followed by the serial number), comply with the requirements of the COUNCIL'S DIRECTIVE:

- Directive "relating to machinery" **2006/42/EC**.
 - Particular requirements for robotic battery powered electrical lawnmowers **EN 50636-2-107: 2015**
 - Electromagnetic fields **EN 62233: 2008**.
- Directive on "restriction of use of certain hazardous substances" **2011/65/EU**.
- Directive "relating to noise emissions from outdoor equipment" **2000/14/EC**. See also *Technical data on page 51* for information regarding noise emissions and the cutting width.

The notified body 0404, RISE SMP Svensk Maskinprovning AB, Box 7035, SE-750 07 Uppsala, Sweden, has issued a report regarding the assessment of conformity according to annex VI to the Council's Directive of May 8, 2000 "relating to noise emissions into the environment" 2000/14/EC. The certificate is numbered: 01/901/287 for GARDENA SILENO city and for GARDENA smart SILENO city.

- Directive "relating to radio equipment" **2014/53/EU**. The following standards have been applied:
 - Final draft **ETSI EN 303 447 v1.1.1** (2017-06)
- Electromagnetic compatibility:
 - **ETSI EN 301 489-1** Draft v2.2.0
 - **ETSI EN 301 489-52** Draft v1.1.0
 - **ETSI EN 301 489-17** Draft v3.2.0
 - **ETSI EN 301 489-19** v2.1.0
 - **ETSI EN 300 328** v2.1.1
- For GARDENA smart SILENO city equipped with smart system device also:
 - **ETSI EN 301 489-3** v2.1.1
 - **ETSI EN 300 220-1** v2.4.1
 - **ETSI EN 300 220-2** v3.1.1



Huskvarna 2017-11-01

Lars Roos

Global R&D Director, Electric category

(Authorized representative for Husqvarna AB and responsible for technical documentation.)



ORIGINAL INSTRUCTIONS

We reserve the right to make changes without prior notice.
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